Redefining possible*

Countering the Evolving Drone Threat

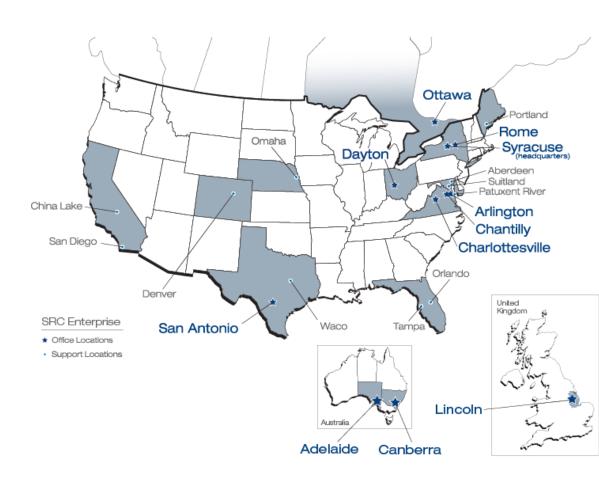
The Need for a System-of-Systems Approach



Defense > Environment > Intelligence

Who Is SRC?

- Founded in 1957 as a "Not-for-Profit" Research & Development company
 - Earnings reinvested into company – No stockholders
 - Technology innovation, state-ofthe-art RF, EW systems
- Today: End to End product design, development, production and life cycle support
 - Focus in Radar and EW system
- ~1,400 employees
- FY19 projected revenue \$340M





What We Do ...

Partners with the U.S. Military on Unmanned Aircraft Systems (UAS) threat since 2005





Electronic Warfare

Data Analysis

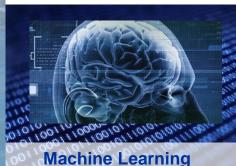
Radars & Sensors



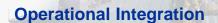




Counter-Unmanned Systems



Primary Provider of C-UAS Technology to The U.S. Military



Intel, Surveillance, Reconnaissance

Environmental Health Analysis



Enabling the Evolving UAS Threat

- ▶ Technology Evolution The accelerating pace of UAS Capabilities
- Proliferation Low/Decreasing cost and ease of access



- Command & Control System Improvements
 - Autonomy: Ease of Use AI & ML Masses/Cooperative Swarms
 - Command & Data links Encrypted/encoded/frequency hopping
 - Improved guidance Satellite, Inertial, Optical, hybrid



- Smaller & Quieter ... Harder to detect/track
- Longer Range/Endurance ... Increased threat envelope
- Payloads
 - ISR payload improvements More stand off range
 - Lethality ... Increased payloads & autonomous targeting







Redefining possible*

This Threat Requires

A SYSTEM-OF-SYSTEMS APPROACH

Detection, Identification, Decision and Defeat

Counter-UAS Functional Requirements

Detection & Identification				Decide	Defeat		
Radar	Spectrum Sensing/ Geolocation	EO/IR Camera	Acoustics	C2/User Interface	Electronic Warfare (EW)	Laser/ High Energy RF	Kinetic
•All UAS Ops Modes •Primary	•Command Link Ops - "Primarily"	•AII UAS Ops Modes	•All UAS Ops Modes	•All UAS Ops Modes	•All UAS Ops Modes •Primary	•All UAS Ops Modes	•All UAS Ops Modes •Primary
Function: Air Vehicle Detection/ Tracking - All Ranges (10+km) •Secondary Function: Target Confirm	•Primary Function: Air Vehicle/ Controller Detection/ Geolocate •Secondary Function: ID/ Confirmation	•Primary Function: ID/Confirmation •Secondary Function: Tracking/ Geolocate •Range: Daylight >5 km; Night ~2 km	•Primary Function: Detection (Short Range < 1km) •Second- ary Function: Direction Finding (DF)	•Primary Function: Integrated Common Operating Picture – All Sensors •Secondary Function: Sensor & Defeat Command Interface	Function: Non-Kinetic "Defeat" of UAS • Jamming, Spoofing, Cyber	•Primary Function: Disruption/ Destruction of Air Vehicle	Function: Disruption/ Capture/ Destruction of Air Vehicle

NO SINGLE PRODUCT OR SYSTEM CAN ADDRESS THE COMPLEXITIES OF THE UAS THREAT



Detection Mechanisms

Active Command Link Operation Mode

- Long Range: >5km
 - <u>Drone</u>: Radar and/or Spectrum Sensor/DF <u>Controller</u>: Spectrum Sensor/DF
- Medium Range: 2km 5km+
 - <u>Drone</u>: Radar, Spectrum Sensor/DF, EO/IR <u>Controller</u>: Spectrum Sensor/DF, EO/IR
- Short Range: <2km
 - o **Drone**: Radar, Spectrum Sensor/DF, EO/IR, Acoustic **Controller**: Spectrum Sensor, EO/IR

Autonomous Operation Mode

- Long Range: >5km
 - o **Drone**: Radar **Controller**: Spectrum Sensor/DF (@ Startup Only)
- Medium Range: 2km 5km+
 - o Drone: Radar, EO/IR Controller: Spectrum Sensor/DF (@ Startup Only), EO/IR
- Short Range: <2km
 - <u>Drone</u>: Radar, EO/IR & Acoustics <u>Controller</u>: Spectrum Sensor (@ Startup Only)



Identification Mechanisms

Controller

- RF Spectrum Sensing, DF and Geolocation
 - Command and/or Data Link Characteristics Threat Library Based

Drone

- Radar
 - Size (RCS) Environment (Birds, RF Domain) Kinematics of UAS Micro-doppler
- RF Spectrum Sensing, DF and Geolocation
 - Command and/or Data Link Characteristics Threat Library Based
- EO/IR
 - Size (Physical) Kinematics of UAS Environmental (atmospherics, clutter, birds)
- Acoustic
 - Size/Mass and Propeller No. and Design Environmental (Atmospherics, Noise Spectrum)



Decision Mechanisms - C2 & User Interface

Primary Functions

- Integration of Sensor Inputs
- Presentation of a Common Operating Picture

Secondary Functions

User Command Interface for Sensors and Defeat Mechanisms

Open Architecture Essential

- Pace of threat evolution and Myriad of components/systems available ... flexibility required
- Increasing use of AI & ML to support work loads and decision aids



Defeat Mechanisms

Countermeasure is driven by the <u>UAS</u>, the <u>Mission</u> and <u>Environment</u> of the engagement

Non-Kinetic Mechanisms

- **EW (Jamming, Spoofing)** Cost effective but operational environment limitations
- Cyber Limited/continuously evolving set of applicable drones
- Low energy Laser Dazzlers Optical Seekers or Video Cameras
- High Energy Lasers Expensive and "not there yet"
- **High Energy Microwave/RF** Promising but collateral risk is present

Kinetic Mechanisms

- Guns High collateral damage risk with lower P-Kill
- Rockets/Missiles Effective but Cost Ratio is currently non-supportable
- Netting Systems Effective for single drones, but at very short ranges
- Capture Drones Diminished effectiveness against swarms/masses



Trends We See Today in Counter UAS Needs.....

Increased AI & ML implementation – Autonomy

• Threat: Both Air Vehicles & Controllers ... C-UAS: Primarily in C2/GUI But also Sensors & Defeat

Radar

- "On-the-Move" capabilities ... Significant mission flexibility improvements
- Multi-Mission/Multi-Function ... Cost Ratio improvements
- Dual/Multi-Band Systems to address RF spectrum conflicts
- "Passive Radar" ... not there yet, but promising/possible

→ EO/IR

- Increasing Detection Range with Optical Tracking and Discrimination/Identification
- Improving Environmental/Atmospherics Conditions Performance Optics and Processing Improvements

EW/DF

- Multi-mission Simultaneous C-IED, Counterfire and C-UAS
- Improving DF/Geolocation and Identification
- "Surgical" Jamming/Spoofing/Hacking
- Swarm Defeat Mechanisms

Other Defeat Mechanisms

- Lasers High and Low Energy
- · High Energy Microwave
- "Cooperative" Anti-Drones
- "Smarter", Lower Cost Kinetic Kill/Capture



Redefining possible*

Silent Archer®

Mission Configurable Counter-UAS Technology

Family of C-UAS System-of-Systems Solutions

Core Silent Archer Components

Air Surveillance Radar

Electronic Warfare System

Direction Finding Unit

EO/IR Camera

User Display



- LSTAR® air surveillance radar
- Gryphon R-14103-D full AESA radar
- SkyChaser™
 On-The-Move radar





- EWSS (USG)
- SRC / Micro transceiver
- Allen-Vanguard
 ANCILE™
- 3rd Party EW





- Gryphon S1200 Spectrum Sensor
- TCI Model 280
- 3rd Party DF



- Night Hawk by PVP Advanced EO Systems
- Camera agnostic
- User Defined



- Silent Archer 3-D
 User Interface
- Gryphon
 Skylight[®] Airspace
 Monitor Interface
- Customerspecified C2



Experience Counts





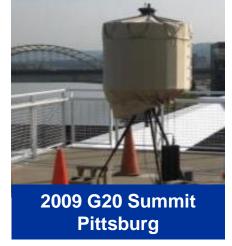


SRC Silent Archer®









Can You Guess Where?





Thank You

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