



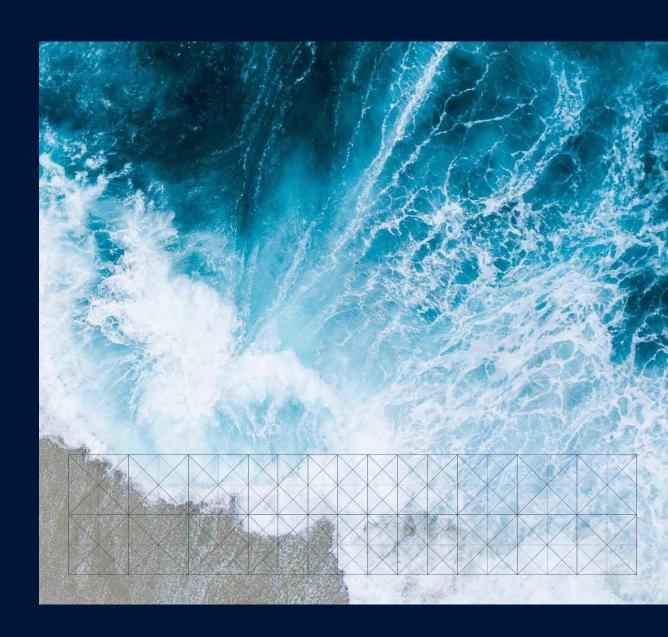
**DSEI 2019** 

# TOWARDS REMOTE & AUTONOMOUS SHIPPING

London, September 11<sup>th</sup>, 2019

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SVP Concept & Innovation, Kongsberg Maritime



## **MARINE TRENDS**

## **Digitalization**

End Customer

Remote & **Autonomous**  **Platform** 

**Economics** 

## **Environment**



Renewables

CO<sub>2</sub> and

**Green House** 

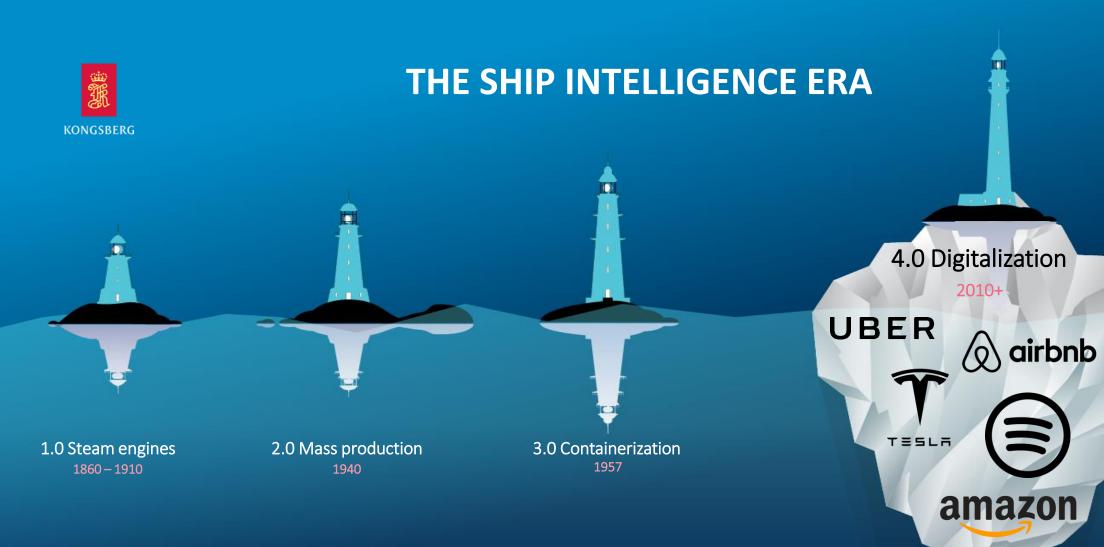
**Emissions** 





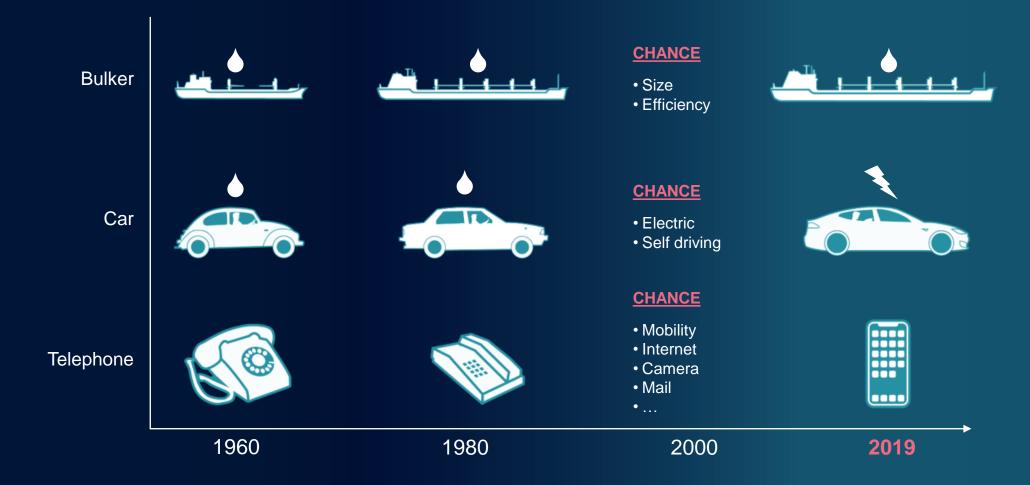
## Disruptive change

by digitalization





## TIME FOR CHANGE!





## **CHANGE DRIVEN BY DIGITALIZATION**













## **DRIVERS FOR R&A SHIPPING**











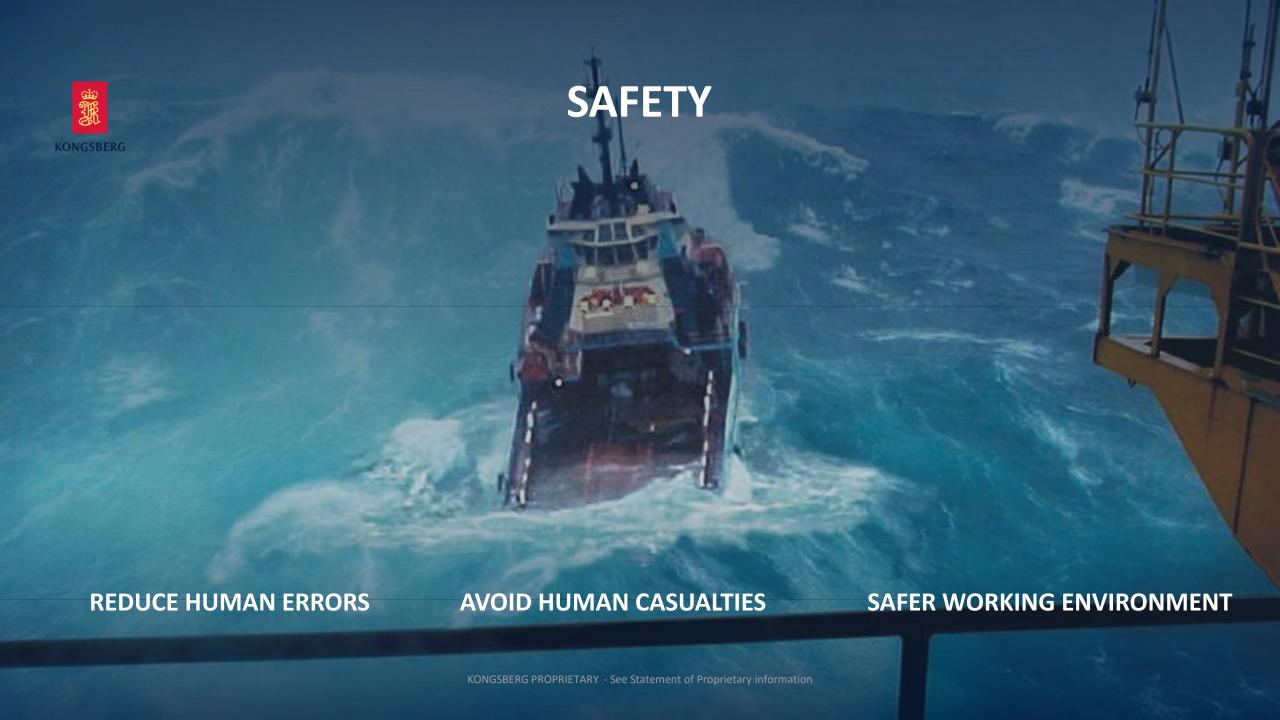
**SAFETY** 

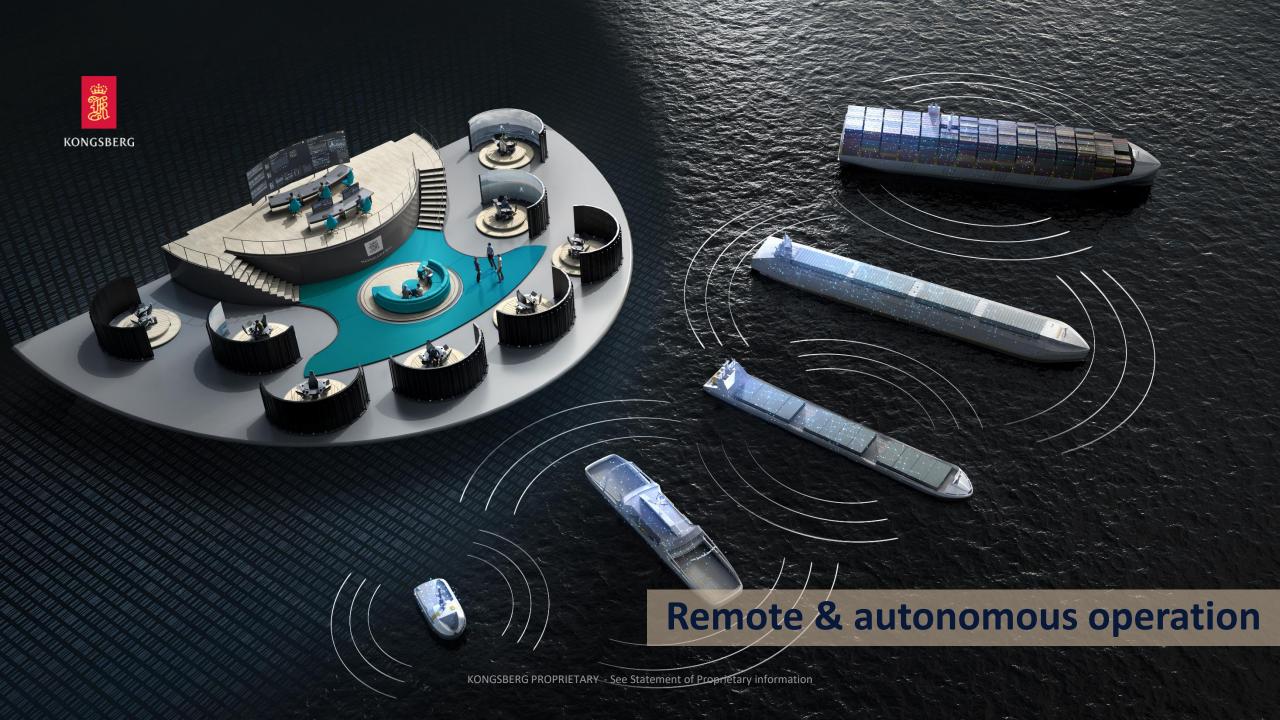
**MONEY** 

**SUSTAINABILITY** 

**RISK** 

**BUSINESS** 









## **AUTONOMY VS MANNING**

There is not one concept that fits all

FULL AUTONOMY								
CONSTRAINED AUTONOMY				_		R		
MONITORED AUTONOMY					<del></del>	-		
ADVISORY	Managaria.					_		
NO AUTONOMY				-				
ONBOARD	FULL MANNING	REDUCED MANNING	PERIODICALLY UNMANNED	MANNING ONBOARD	PERIODICALLY UNMANNED	NO CREW ONBOARD		
ASHORE	NO SHORE CONTROL			REMOTE OPERATION		REMOTE OPERATION	REMOTE SUPERVISION	NO CREW ASHORE

### MANNING



## UNMANNED OR CREW ABOARD?

There is not one concept that fits all

	Normal manning R&A technology	Low manning R&A technology	Unmanned Full scope
Bulker	i MM	i ma	imm
General cargo			
Feeder container			
Large container	Ymmymmmm <sup>2</sup>	ļ	
Tanker		di .	
LNG/LPG			
OSV			
Tug	المناب المناب المناب	-	-
Road ferry	-	-	-
RoRo			
RoPax			
Cruise			



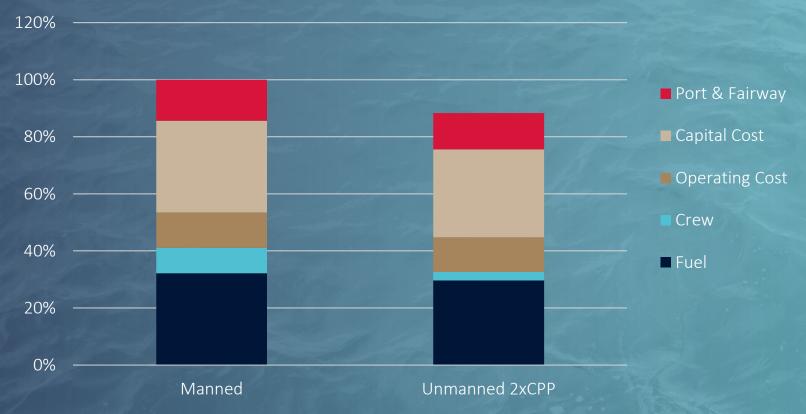


## **UNMANNED ECONOMICS**

Bulker 35 000 DWT

Relative annual cost of cargo transport

Example: total transport cost for a 35k DWT bulker results in economic gain for the unmanned concepts (~12%)

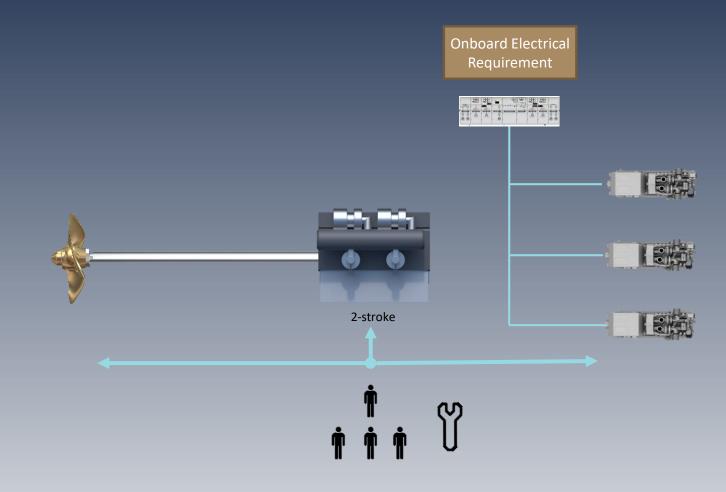




## THE CHALLENGE OF UNMANNED MACHINERY

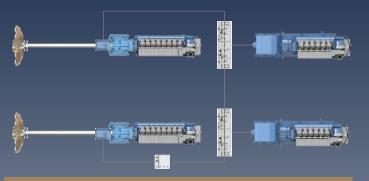
Traditional cargo vessel machinery reliability

- Traditional 2-stroke mechanic propulsion
- Both components and system are not designed for unmanned operation
- Reliability is maintained by having human engineers available 24 hours per day.



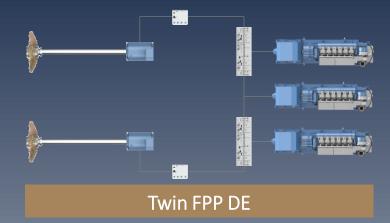


## PROPULSION AND MACHINERY FOR RELIABILITY



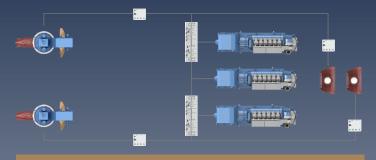
#### Twin CPP Hybrid

- Simplest machinery that offers redundancy, however reduced propulsion capability if ME failure
- Cost: +120-160% of traditional
- Propulsion Reliability: +



- Diesel electric system allowing for small consequence of Main Gen-Set
- Cost: +200-240% of traditional
- Propulsion Reliability: ++

failure



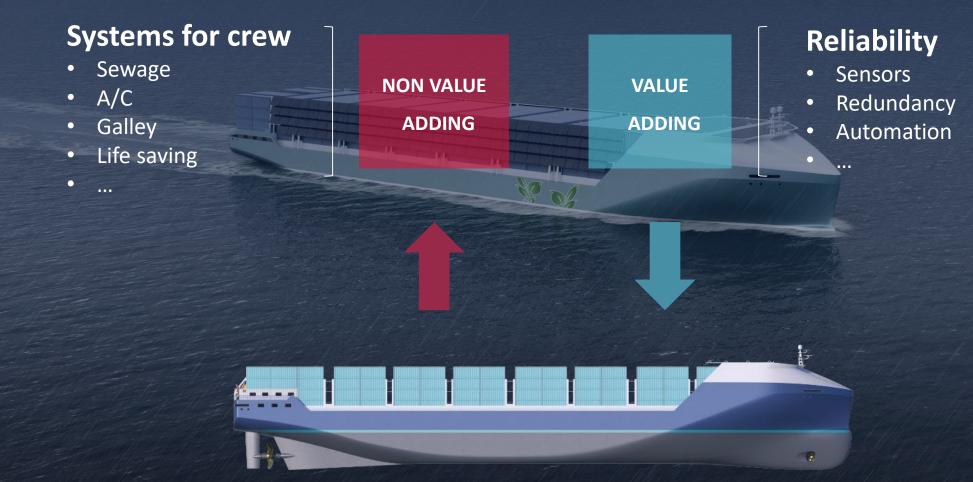
#### Pod DE

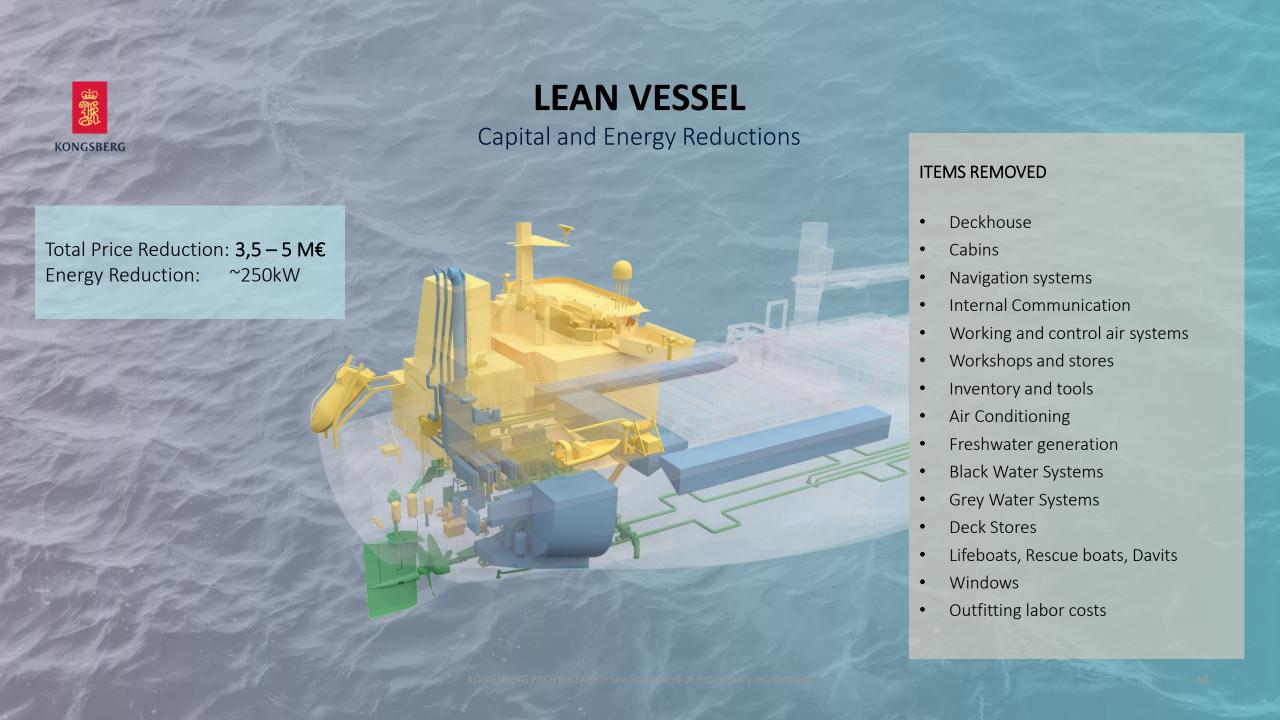
- Diesel electric system allowing for small consequence of Main Gen-Set failure
- Cost: +220-260% of traditional
- Propulsion Reliability: ++
- Additional maneuverability benefit



## **UNMANNED SHIPPING**

How to go from low cost to high end systems



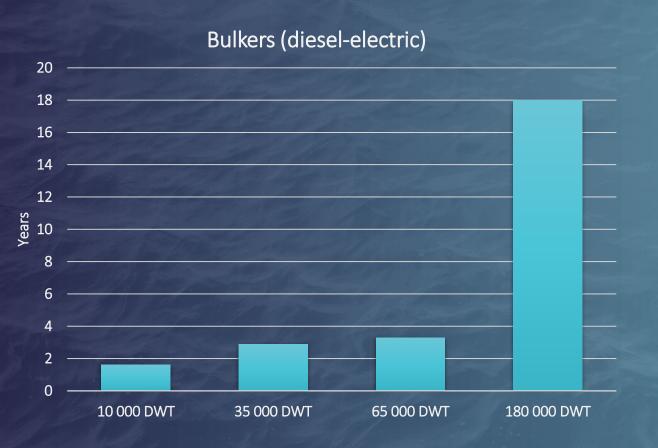


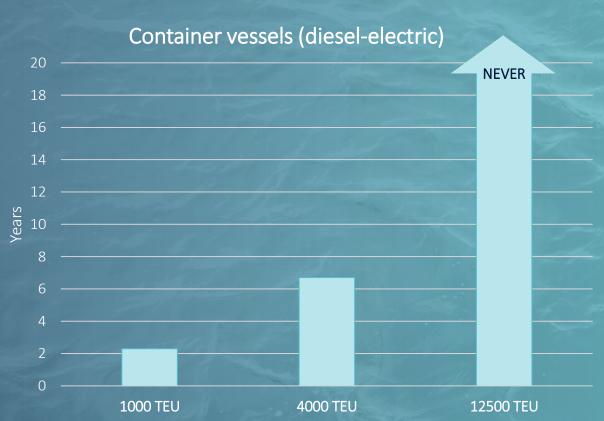




### **UNMANNED ECONOMICS**

Unmanned vessel payback periods









## **EARNINGS AT DIFFERENT MARKET CONDITIONS**

Manned versus unmanned in freight market

FREIGHT RATE: 8.4 \$/T

#### Unmanned

Speed: 11 knots

Earnings: \$163 / Day

#### Manned

- Cannot offer transport without making a loss
- Layup, or take voyage at loss

FREIGHT RATE: 9.5 \$/T

#### Unmanned

Speed: 12 knots

Earnings: \$2 918 / Day

#### Manned

Speed: 12 knots

Earnings: \$789 / Day

FREIGHT RATE: 14.5 \$/T

#### Unmanned

Speed: 13 knots

Earnings: **\$16 427 / Day** 

#### Manned

Speed: 14 knots

Earnings: \$14 270 / Day

FREIGHT RATE: 17.1 \$/T

#### Unmanned

Speed: 14 knots

Earnings: \$ 23 274 / Day

#### Manned

Speed: 14 knots

Earnings: **\$21 376 / Day** 











## WORLD'S FIRST REMOTELY CONTROLLED COMMERCIAL TUG

KONGSBERG and Svitzer Remote Control Demo in 2017





## WORLD'S FIRST REMOTELY CONTROLLED COMMERCIAL TUG

KONGSBERG and Svitzer Remote Control Demo in 2017





## **Automatic Crossing System**

More than 20 System in operation or on order!







## WORLD'S FIRST AUTONOMOUS FERRY – FINFERRIES FALCO

SVAN is a demonstration (2018) of the world's first remote and autonomous ferry with a focus on improving the safety and efficiency of vessel operations and supporting the crew.





## **WORD'S FIRST AUTONOMOUS FERRY**





Remote Control Station









## The Challenges



## **RELIABILITY**

How to ensure that all systems are available at sea



STANDARDIZATION

**VALIDATION** 

HEALTH MANAGEMENT SENSORS AND TRENDING

**DIGITAL TWINS** 







## **RULES & REGULATIONS**





SOLAS





## **DEFINITIONS**

Maritime Autonomous Surface Ship (MASS) =

"a ship which, to a varying degree, can operate independently of human interaction"

MASS autonomy levels	Description		
Ship with automated processes and decision support	Seafarers are on board to operate and control shipboard systems and functions. Some operations may be automated.		
Remotely controlled ship with seafarers onboard	The ship is controlled and operated from another location, but seafarers are on board.		
Remotely controlled ship without seafarers on board	The ship is controlled and operated from another location. There are no seafarers or board.		
Fully autonomous ship	The operating system of the ship is able to make decisions and determine actions by itself.		

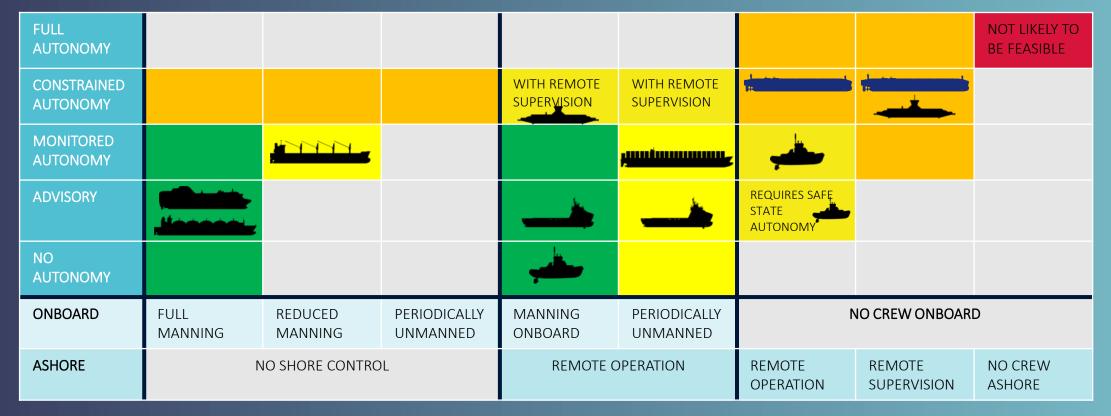




## **AUTONOMY VS. MANNING**

Regulative point of view

VERY CHALLENGING
TO GET ACCEPTED



**MANNING** 

CAN BE COVERED BY TODAYS RULES



## PATHS TO R&A SHIPPING

