Where Courage Meets Technology

VECTOR SENSOR FOR HF DIRECTION FINDER

A REVOLUTIONARY WAY TO TACKLE THE HF CHALLENGE

ELTA Systems Ltd.

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HF is not dead...







Exclusive Economic Zone (EEZ) protection









Accessible

- Cheap
- Physical characteristics
- Advanced generation:
 - Digitized
 - FF\FH
- Hard to Geo-Locate



Conventional HF DF Ground System



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And why is that?

A journey to high school physics...



Wavelength for HF vary from 10 to 100 m

Conclusion – interferometer will require multiple antennas over large area



HF Interception in Airborne Systems







3D Aerial HFDF

New Technology for

Instantaneous Geo-Location







Poynting Vector Theorem





Vector Sensor - Basics

- The DF estimated direction is a 3D (i.e. azimuth and elevation)
- Vector Sensor Array (VSA) on aerial platform enables the intersection of the 3D direction with a Digital Terrain Map (DTM) establishing a geolocation from a single platform.



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Airborne Implementation Compact & Light Weight HF DF Antenna Array





The Airborne VSA HFDF System Units



Antenna Array

Multi- Channel COMINT Sensor (MCCS)



Enhancing The Location Product

Integration of measurements enhances the location product



HF DF cues the optical sensor – Typical Display





- Physically small compact Vector Sensor antenna (VSA) array
- Instantaneous azimuth (360°) and elevation (± 90°)
- Instantaneous geo-location utilizing DTM!
- Accuracies better than 2° RMS
- All modulations & polarizations
- No Skip Zone
- Suitable for various manned and unmanned aerial platforms







Flight Demonstration

on

HERON 1 UAV







Flight on S-100 VTOL

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Example: installation on S-100 VTOL UAS Integrated HFDF - EO





The AUSTRALIAN ARMY Exercise



https://www.uasvision.com/2018/12/14/schiebel-camcopter-s-100-successfully-demonstrates-new-comint-and-imaging-payloads-to-australian-army/

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Ground Based Implementation

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Ground Based Vector Sensor Antenna Array

The Principle: DF using Poynting vector

 $S = E X H^*$

The Implementation



R= 60 cm H= 120 cm 18 kg

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The Ground HF DF implementation

- Distinction between sky-waves and ground waves
- Instantaneous Azimuth, Elevation and polarization
- DF accuracy better than 2° RMS
- Single Site Location (SSL) for sky waves

The Principle: DF using Poynting vector

 $S = E X H^*$



H= 120 cm, R= 60 cm, W= 18 Kg



HF DF Comparison Table

Typical Fixe	ed HF Df Systems	Typical Mobile HF DF Systems	ELTA's new 3D HFDF Mobile/Fixed Solution
Method	Interferometer	Watson Watt	Vector Sensor
Size	10000 m²	3 m	1.2 m 🌏
Deployment Time	3 hrs	Mobile 🥑	Mobile 🥑
Accuracy@Low Elev.	2° 🥑	5-10°	2° 🧭
Azimuth	360°	360°	360°
Coverage		· ·	-
Elevation	0-85° 👩	None	0-90°
Coverage			
SSL	Yes 🥑	No	Yes 🧭
Instantanues measurement Ground & NVIS	No	No	Yes 🥑
Frequency Range	2-30 MHz 🛛 🕢	2-20 MHz	1.5-30 MHz 🧭



Naval HFDF - The new solution

- The advantages:
 - **& Low signature (Compact DF Antenna Array)**

 - **«Better (>2 times)** accuracies
- The principal:
 - **«Vector Sensor antenna**



R= 60 cm H= 120 cm 18 kg



THANK YOU

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