

#### SUBSEA TECHNOLOGY

# Fusing sensor data for improved MCM performance using AUVs UDT 2018

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> POSITIONING NAVIGATION COMMUNICATION MONITORING IMAGING

#### Overview









- Increase Search Classify Map (SCM) Survey Area.
- Increase Mission Quality and Tempo.
- Improve Percentage Clearance.



- Improve Probability of Detection (PD).
- Decrease Probability of False Alarms (PFA).
- Improve Accuracy of Survey.
- Coverage Rate.







#### **AUV Navigation**



# "Today we can navigate with centimetre

accuracy"

#### **AUV Navigation**





## Gravity

## Rotation



Image created by Reto Stöckli, Nazmi El Saleous, and Marit Jentoft-Nilsen, NASA GSFC

#### **AUV Navigation**

VIII III





# DVL & Acoustic Aided INS

#### **AUV Tracking & Communications**



# "Today we can track and communicate across full Ocean depths."



#### **AUV Tracking & Communications**



Sound in depth

#### **AUV Tracking & Communications**



Battery: 95% Status: Green Mission: W4 Lat: 50.33503° Long: -4.160042°

## "Track and Communicate with AUV"



#### **AUV Navigation**



Relative navigation cm scale

## **DVL & Acoustic Aided INS**

**Ultra-high definition Multi Aperture Sonar** 



#### Ultra-high definition Multi Aperture Sonar









### Shape of highlight and size of shadow is used improve PD and to limit PFA



PALEINGER MARINE

#### Ultra-high definition Multi Aperture Sonar



#### **Dynamic Focusing**





Best in Class Along Track Resolution  $0.15^\circ$ 



- Increased contrast and ultra-high definition:
  - Better estimates of highlight and shadow pairs
  - Better operator decisions
  - Better ATR performance
- Dynamic Focusing:
  - Improved PD and PFA across the whole swath
- Multiple Apertures:
  - Improves SNR reducing "speckle"
- MAS:

Improves Percentage Clearance and effectiveness of mission





Sound in depth















- Open interfaces .SWF8
- Real-time ATR Interface
- PMA integration into 3<sup>rd</sup> Party Software
- Compatible with leading PMA software:
  - Triton Imaging
  - HYPACK
  - Cheasapeake
  - SeeTrack
  - CARIS
- Many in development
- Simpler integration to AUV



Sonardyne

#### Multi Aperture Sonar for Low-logistic AUVs

- Hydrophone Array Length 672mm
- Frequency Band 725 to 775 kHz
- Bandwidth 20 kHz
- Swath 200m
- Depth Rate 200m
- Operating Power 18W



- Already integrated with leading suppliers
- Low-logistic platforms
- Ultra-high resolution sonar

![](_page_22_Picture_12.jpeg)

![](_page_22_Picture_13.jpeg)

![](_page_23_Picture_2.jpeg)

![](_page_23_Figure_3.jpeg)

# AUV

![](_page_24_Picture_2.jpeg)

![](_page_24_Picture_3.jpeg)

- AHRS alignment for instant INS initialisation
- Mechanically aligned and tightly coupled for improved performance and flexible deployment options
- Access each instrument or simply interface to INS
- Sparse LBL aiding with 6G beacons
- Battery for continued INS function even during power failures
- In built storage for Post-Processing and QA
- Water blocks to keep electronics safe
- Beam level aiding for better performance and robustness even in difficult seabed conditions

![](_page_24_Picture_12.jpeg)

Integrated AUV Navigation and MAS

![](_page_25_Picture_2.jpeg)

Interferometry provides 3D View of World

![](_page_26_Picture_1.jpeg)

Integrated AUV Navigation and MAS

Max Depth: 24m (79 feet) Location: 50°19.54N; 4°14.65W Length: 130 metres (427 feet)

Description: 7,000 ton US Liberty Ship, hit by a torpedo from a German U-boat near the Eddystone reef. The James Egan Layne was towed towards Whitsand Bay near Plymouth in order to save the cargo. However, on the way back, her stern collapsed causing her to sink.

![](_page_26_Picture_5.jpeg)

- May 2014 PLEM inspection
- Bluefin-12 AUV
- Pipeline End Manifold used to import LNG
- Large Template 12 x 12 m, pipe and mattress protectors
- The individual elements of the mattresses 0.25m by 0.25m

![](_page_27_Picture_7.jpeg)

![](_page_27_Picture_8.jpeg)

![](_page_28_Picture_2.jpeg)

![](_page_29_Picture_2.jpeg)

![](_page_30_Picture_2.jpeg)

- Increase Search Classify Map (SCM) Survey Area.
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![](_page_31_Picture_0.jpeg)

#### SUBSEA TECHNOLOGY

### Thank you for your time today Any questions?

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![](_page_31_Picture_4.jpeg)

POSITIONING NAVIGATION COMMUNICATION MONITORING IMAGING