

US Army Next Generation Breaching Technology – Explosive Breacher





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What do US Army Engineers Do?



Mobility

- Obstacle Breaching
- Gap crossing

Counter Mobility

- Close
 - Lethal
 - Non-lethal
- Mid/Deep
- Physical
 - Ditches
 - Fence

Survivability/General Engineering

- Blast mitigation
- Vehicle and Soldier protective positions
- Infrastructure
- Route repair & maintenance
- Airfield damage repair
- Port opening & repair

How do we do this in the future?



















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Mobility



Breaching – now



Explosive

Ineffective against modern complex min<u>es</u> Slow to reload Not scalable for deep obstacles

Mechanical

Soldier in the breach Slow <10km/hr Bespoke equipment, hard/expensive to repair/replace

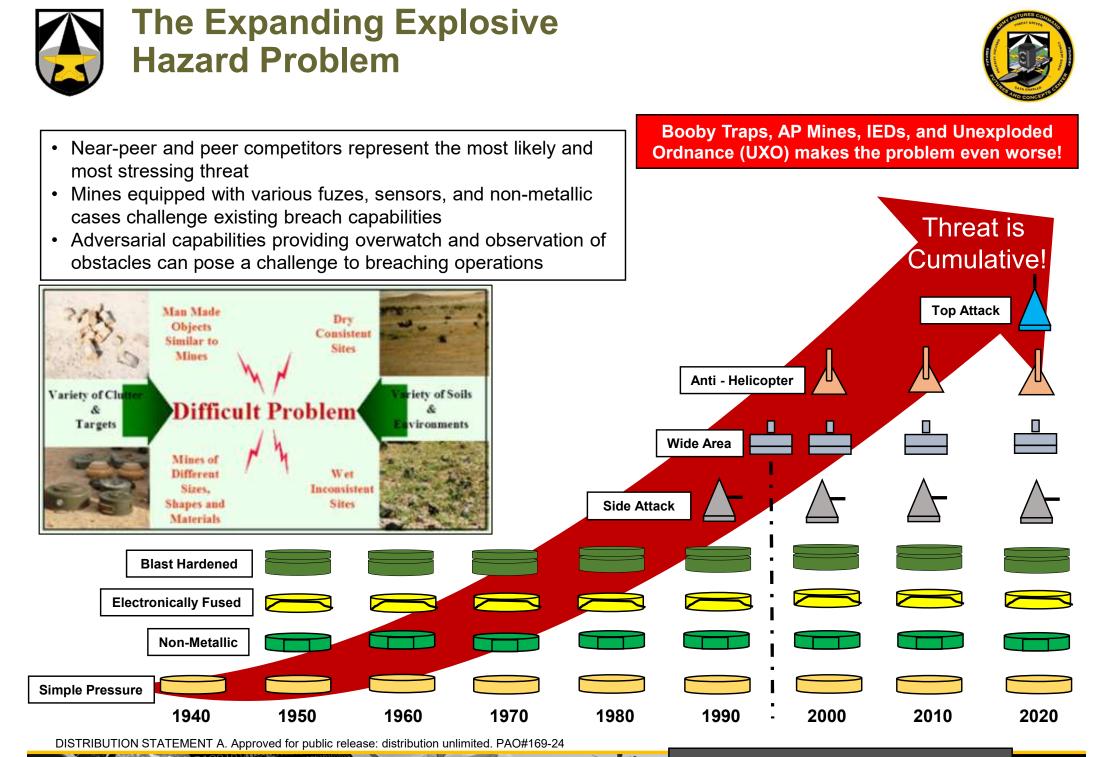
Future

Effective against all explosive threats Quick and efficient to reload (minimal Trg required) Scalable for deep obstacles

Autonomous Inexpensive or highly resilient











Why Should we modernize?

- Peer and near peer adversaries continued to modernize their obstacle capabilities by leveraging technology. While US has been in counterinsurgency (COIN) operations for 20yrs.
- The Research and Analysis Center (TRAC) to conduct a Complex Obstacle Reduction in Multi-Domain Operations (CORMDO) Study. Citing 14 out of 33 NTC rotations from 2014-2018, Mine Clearing Line Charge (MICLIC) Operational Readiness (OR) rate for the launchers fell below 50% vs requirement of 78%.
- Modeling scenarios results showed 100% catastrophic damage with 50% redundancy, and 0% completion of any of the complex obstacle reduction.
- In Jan 2019, the House Armed Service Committee report cited the MICLIC deficiencies of sustainability and age of the line charge averaging of 25 yrs.

Concluding To maintain freedom of maneuver for the fight tonight. The Army must continue to improve the RAM, effectiveness and survivability of current breaching systems. To overcome these limitations in the future, there needs to be investments into testing, development, suitability, and feasibility to support the Armed Forces freedom of maneuver of 2030-2040.

Enables key Army modernization initiatives by accomplishing:

- The GOBLN capability will provide Increased stand-off for 1) Detection/Targeting 2) Neutralization 3) Digital Marking 4) Reporting.
- Proportionate neutralization to the threat obstacle, Modular Mission Payload to current and future prime-movers vehicles (i.e., Robotic Combat Vehicle (RCV), Assault Breaching Vehicle (ABV), & Optional Manned Fighting Vehicle (OMFV)).
- Integration in the future with near real time Common Operating Picture updates via remote explosive hazard and obstacle identification by incorporating geospatial data into mission command systems.

Training:

- The MICLIC has been unit trained since first unit equipped and continues to be train the trainer, as a perishable skill.
- GOBLN vision for training is to utilize training simulators, training rounds, and capstone with live fire training/qualifications. This may require a specific Additional Skill Identifier (ASI).

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Background and Capability



Task: Breaching at Standoff

Key Facts

- Next Generation Combat Vehicle (NGCV) Endorsement: MAY 2020
- Acquisition Shaping Panel: 13 JUN 22
- Abbreviated Capabilities Development Document (A-CDD) Requirement Validated by AFC: 6 JUL 22
- Assistant Secretary of the Army for Acquisition, Logistics, and Technology (ASA(ALT) Acquisition Decision Memorandum (ADM) Signed: 3 DEC 22
- Joint Program Executive Office Armaments & Ammunition (JPEO A&A) ADM Signed: 17 MAR 23
- Milestone B (MS B) Planned for *2QFY26

Assumptions

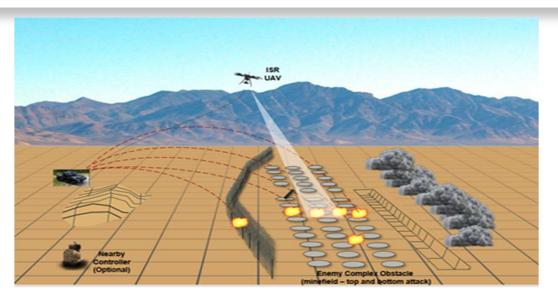
- Future Approved Acquisition Objective (AAO) will mirror trailer mounted MICLIC system
- Leveraging Technology Readiness Level (TRL) 5-6 Government-developed subsystems for an FY24 Concept Demonstration
 - Transitioning NGCV-Cross Functional Team (CFT) endorsed Ground Obstacle Breaching Lane Neutralizer (GOBLN) Science & Technology (S&T) effort developed by Development Command – Armaments Center (DEVCOM-AC) for obstacle neutralization
 - Utilizing DEVCOM-AC S&T automated 81mm mortar system as surrogate neutralization delivery method
 - Utilizing Unmanned Aerial System (UAS) sensor package and Automated Target Recognition (ATR) developed by DEVCOM Command, Control, Computers, Communications, Cyber, Intelligence, Surveillance, and Reconnaissance (C5ISR) Center Research and Technology Integration (RTI)

Capability

- The XM123 GOBLN provides a Modular Mission Payload (MMP) for current and future vehicle platforms that is a reliable, scalable, and capable of providing targeted effects at stand-off ranges against current and emerging explosive and non-explosive obstacles.
- The XM123 GOBLN future remote capability aligns with the NGCV-CFT priorities and Remote Combat Vehicle (RCV) breaching
- Removing Soldiers from the breach area.

XM123 GOBLN is #12 #3 on United States Army Engineer School (USAES) priority list

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Desired Characteristics (DC)			
Priority	Description		
DC #1: System Stand-Off	+/-1KM forward edge of obstacle		
DC #2: Neutralize Explosive Hazards	Current and future Explosive Hazards (EH), up to 150m lane depth in a single combat load.		
DC #3: Detection/ Sensors	Detection/Sensor targeting		
DC#4: Fire Control Station	Manual and remote at +/- 1.6KM.		
DC #5: Scalability	Neutralization proportionate to obstacle.		
DC #6: Modular Mission Payload	Current and future manned or unmanned prime movers.		
DC #7: Load and Reload	Load and reload with organic personnel and equipment in an operational environment		
DC #8: Reporting	Provide obstacle information to the Command Post Computing Environment		
DC #9: Marking	Provide an initial lane marking system by digital means		
DC #10: Reliability	90% chance of successful mission employment		
DC #11: Maintainability	Field Level Maintenance Ratio (MR) will not exceed 0.19 Maintenance Man-hours per Mission		
DC #12: Cyber Survivability	Operate in a cyber-contested environment		

Future breaching capability must reduce obstacles, provide a passable lane for maneuver, and remove Soldiers from the point of breach!

DEVCOM TMRR Concept



Program Description	XM123 Desired Capabilities	
The GOBLN will replace the M58 MICLIC system.	• Standoff +/- 1KM	
 Current and future near-peer counter mobility capabilities challenge current capability Obsolescence / Reliability issues due to average system age of 25 years GOBLN will be a modular, scalable solution providing targeted effects against current and emerging explosive and non-explosive hazards 	 Detect & Neutralize EHs (Current & Future, Surface & Buried) Scalable effects Modular Mission Payload 	IST UAV

Current Government TMRR Concept



Multi-Mission Payload

Capabilities

- Electro-Optical (EO) / Infrared (IR) sensor with on-board ATR processing, data storage, and range-finder capabilities
- Provide real-time situational awareness
- Trained algorithms using real and synthetic data



Automated Direct/ Indirect Mortar

<u>Capabilities</u>

- Modular 81mm platform
- Recoil mitigation, on-board fire control with weapon autolaying, and 20-round autoloader
- Existing Mortar Fire Control System (MFCS) will be tailored for Combat Engineers use



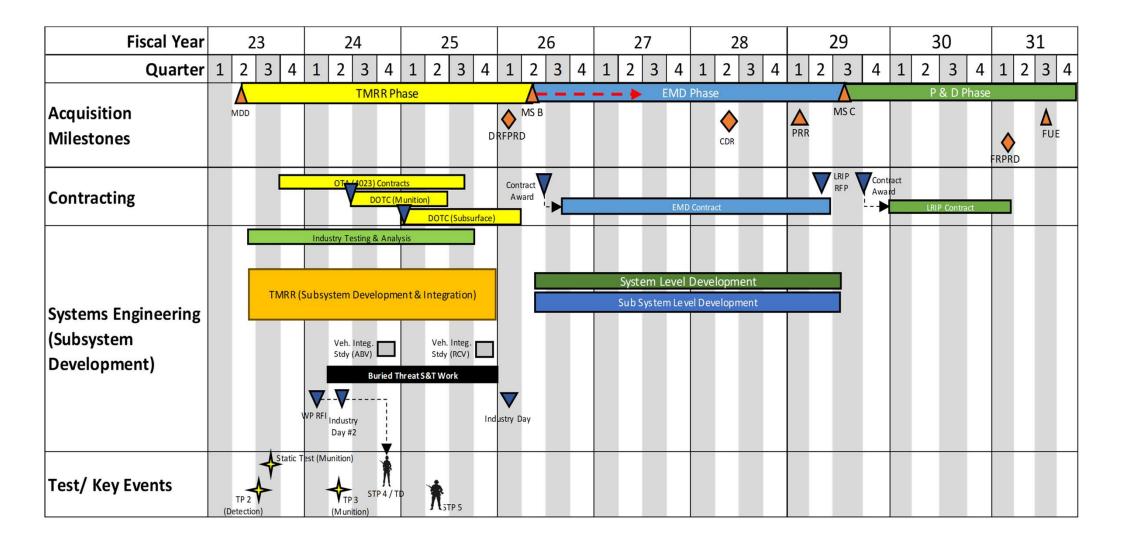
M821A4 (81mm HE)

Capabilities

- In production and qualified.
- Multimode fuse
- Demonstrated effectiveness
 against EHs

Schedule





*** Potential shift in Milestones and all major events to the right by 1 year

XM123 GOBLN Technology Maturation and Risk Reduction Test Strategy





<u>Touchpoint 1</u> <u>Subsystem: Launcher</u> ✓ Conducted Oct 2022 @ Picatinny, NJ <u>Purpose</u> • Demonstrate DEVCOM-AC Launcher subsystem: Automated Direct / Indirect Mortar (ADIM) to support stand-off neutralization concept	Touchpoint 3: Munition Neutralization • Planned 2QFY24 @ YTC, Yuma AZ Purpose • Dynamic live-fire demonstration of 81mm HE Mortar on surface laid targets to determine effectiveness Goals • Determine munition efficacy against surrogate targets	Touchpoint 5: Integration Demo • Planned 2QFY25, Location: TBD Purpose • Final concept demonstration for the user prior to MS B Goals • Final TRL/MRL assessment
Findings Demonstrated modularity, scalability, system stand-off, and remote fire control Demonstrated Firestorm integration Assessed ADIM TRL/MRL 	 Determine munition encacy against surrogate targets Inform Capability Development Document (CDD) requirements Provide forum for industry and government to engage/collaborate Allow Industry to demonstrate alternative munitions 	 Final TRL/MRL assessment Develop cost, schedule, performance planning for EMD Confirm CDD Requirements Inform EMD Contract Prepare for Industry Day post-MS B
Touchpoint 2: Subsystem: Detection ✓ Conducted 12 APR @ FT AP Hill Purpose • Demonstrate DEVCOM -C5ISR's detection sensor payload with Aided Target Recognition (AiTR) • Demonstrate integrated with Firestorm and Mortar Fire Control System • Validated detection at standoff • Validated detection with Firestorm and legacy Mortar Fire Control System. • Assessed TRL/Manufacturing Readiness Level (MRL) of detection concept	Touchpoint 4: Gov't Concept & Industry Tech Demonstration • Planned 4QFY24 @ YTC, Yuma, AZ Purpose • DEVCOM (AC & C5ISR) will demonstrate critical subsystem concepts against a surrogate minefield. • Industry partners will be invited to demonstrate their TRL 6+ concepts (System or Subsystem Level) Goals • Assess TRL/MRL concepts • Inform CDD requirements • Shape Engineering & Manufacturing Development (EMD) strategy • Provide forum for industry and government to engage/collaborate • Allow Industry to demonstrate alternative solutions	<image/>