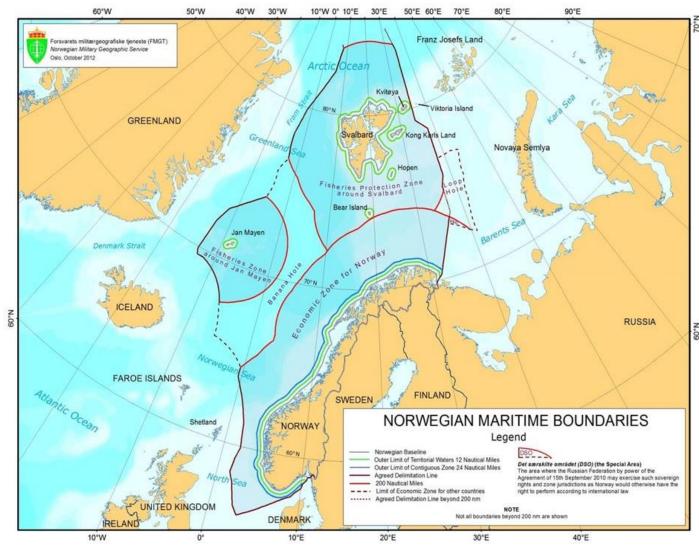


R&D support to Royal Norwegian Navy programs

Håkon S. Andersen Director of Research, Naval warfare systems and Autonomous systems

Combined Naval Event, May 24th 2023, Farnborough

Norwegian maritime boundaries and strategic context



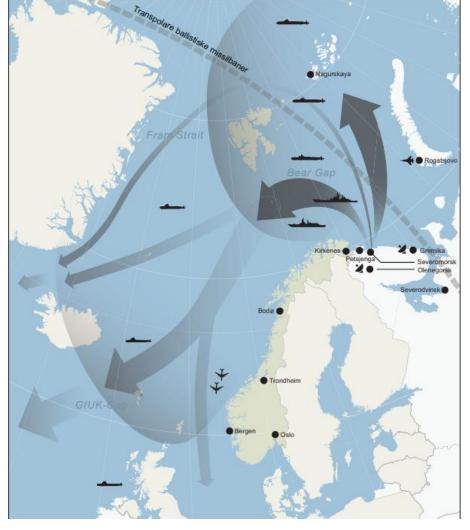
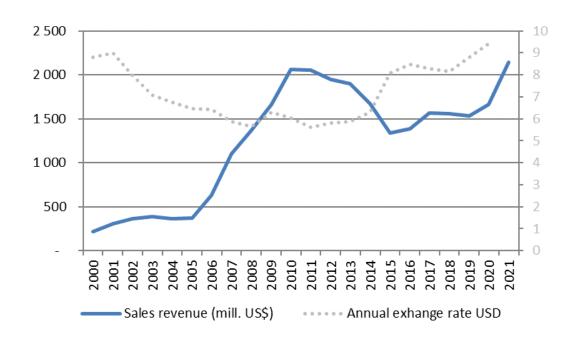


Illustration: 2021 Defence commission / Map: Norwegian polar institute

Image: FMGT

Norwegian defence industry

Sales revenue (mill. USD)





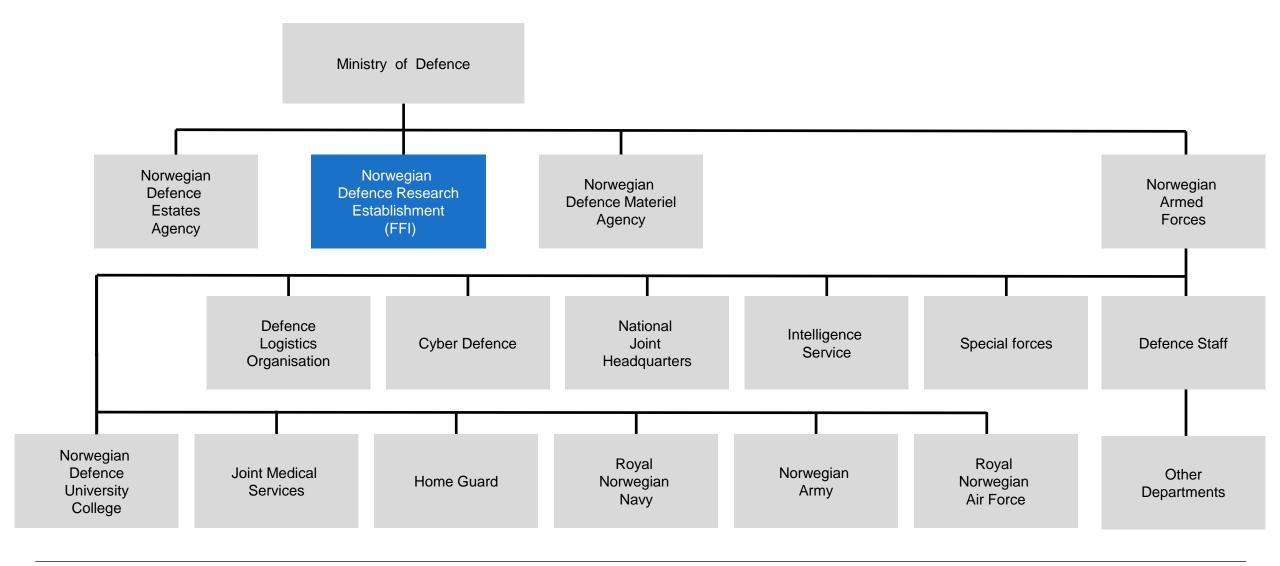






KDA, Nammo, Thales Norway, KAMS (2012 ->) and NFM Group (2009 ->)

FFI in the Norwegian defence sector



FFI in the «defence triangle model»



TRL – The "valley of death" in technology development

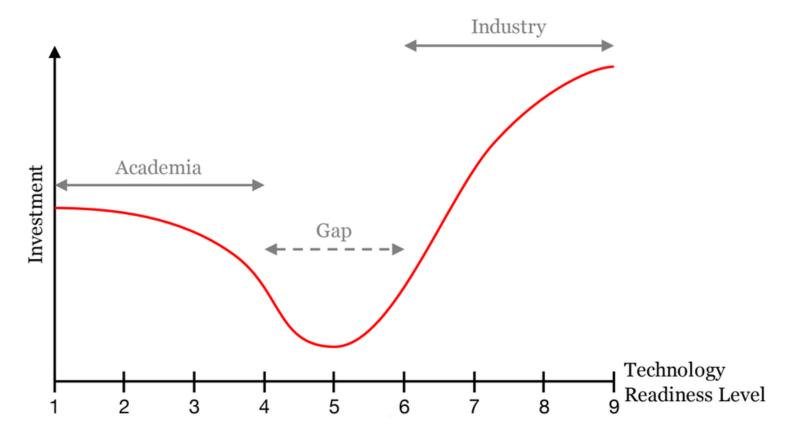


Illustration: https://www.tu.no

Research programs at FFI vs. the "valley of death"

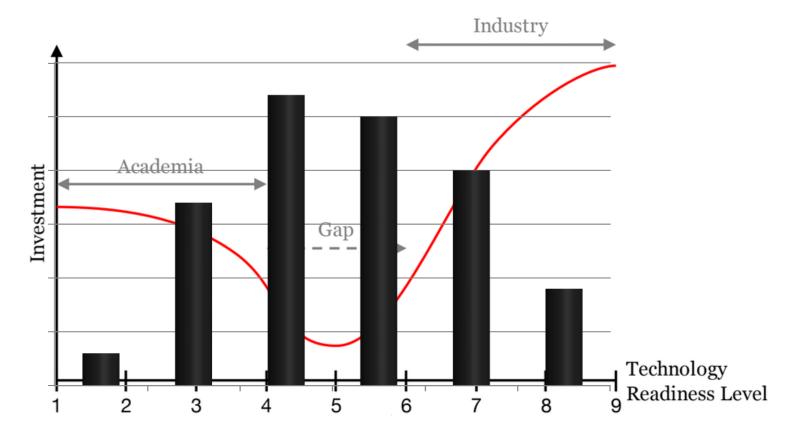


Illustration: https://www.tu.no

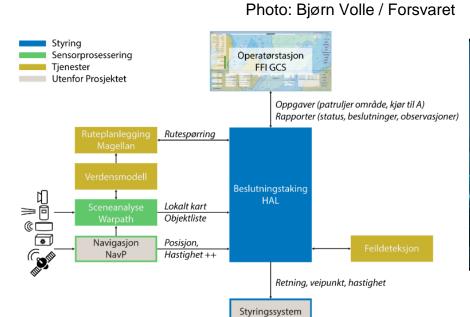
Maritime domain capability development – some ongoing platform related research activities



USV med minesveip

USV med engangsvåpen

USV kontrollerer AUV





Picture: Kongsberg Discovery

Photo: Boeing

Example: Future Norwegian NMCM Capability

 P6359 is the Navy Procurement Program



• 2020 – 2022: Definition phase

• 2023 – 2028: Project phase (IOC: 2026, FOC: 2028)



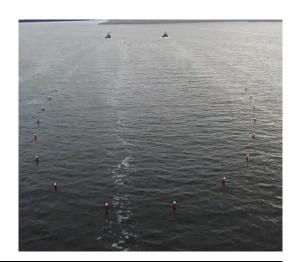




Annual MCM Development Trials











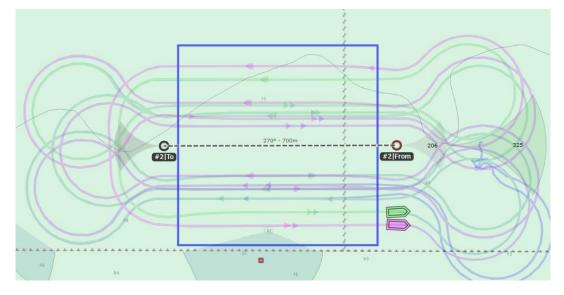
3-week test periods

- Autonomy for MCM
- MCM operations
- Navy participation



FFI USV Autonomy – Key Research Areas 2023

- Sweep operations with 2 USVs in formation
- Route planning with 2 USVs in formation
- Situational Awareness for collision avoidance
- Collision avoidance (iaw selected COLREGS)
- Navigation and positioning accuracy
- Simulator for USV autonomy
- L&R of AUV from USV





FFI

FFI AUV Autonomy – Key Research Areas 2023



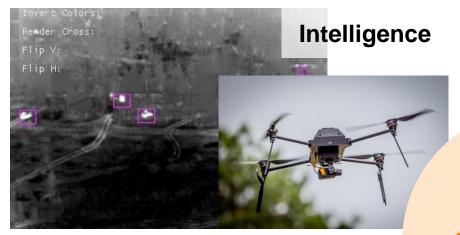
Focus on In-mission processing:

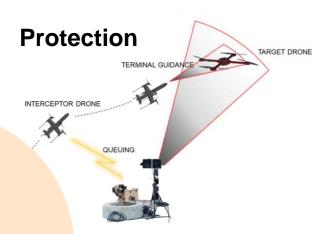
- Terrain Navigation
- HISAS Processing
- INSITE Software (Continuous performance evaluation)
- Adaptive Track Planning
- Change Detection
- Automatic Target Recognition (Algorithms based on deep learning and AI)
- Camera Image Quality Control
- Identification

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Photo: Kongsberg Discovery

Autonomy at FFI - main focus

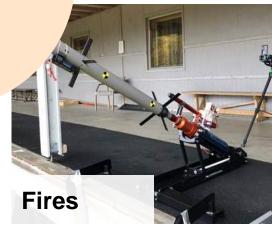






Coordination



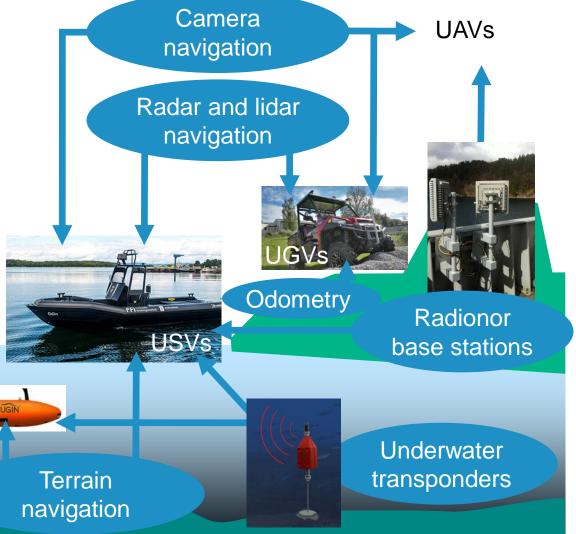




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Navigation in GNSS Denied Environments

Navigation technique researched by FFI





Accurate velocity from multi-element sonar

AUVs

