

# Considerations for an ASW frigate launched unmanned surface vehicle for ASW

Ing. Paul Dröge MA - Commander RNLN







## The Fourth Battle of the Atlantic

*With 'more activity from Russian submarines than we've seen since the days of the Cold War,' an improved European force posture becomes vital for the U.S. Navy and NATO.*

**By Vice Admiral James Foggo III, U.S. Navy, and Alarik Fritz**

June 2016 | Proceedings | Vol. 142/6/1,360

ARTICLE

VIEW ISSUE



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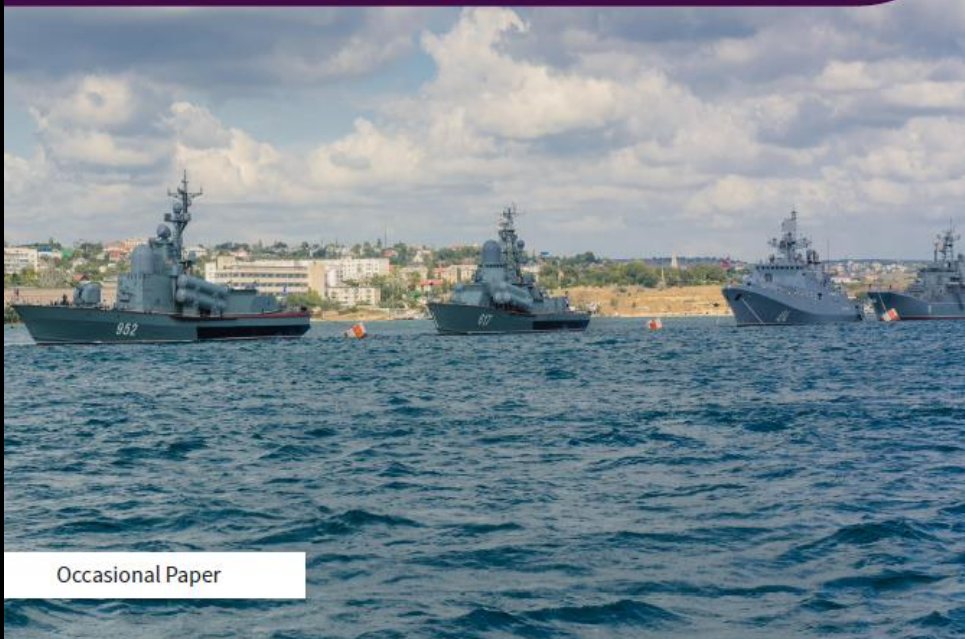


COMMENTS

Occasional Paper

# An Asymmetric Approach to the Use of NATO's Maritime Forces in Competing with Russia

Sidharth Kaushal and René Balletta



Occasional Paper



# Maritime Security in a Time of Renewed Interstate Competition

Navigating the Royal Netherlands Navy through the Geopolitical and Technological Challenges and Threats in the Euro-Atlantic and Indo-Pacific Regions

Paul van Hooft, Davis Ellison and Frederik Mertens

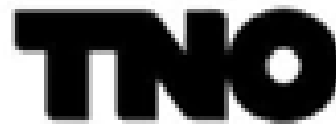
January 2024





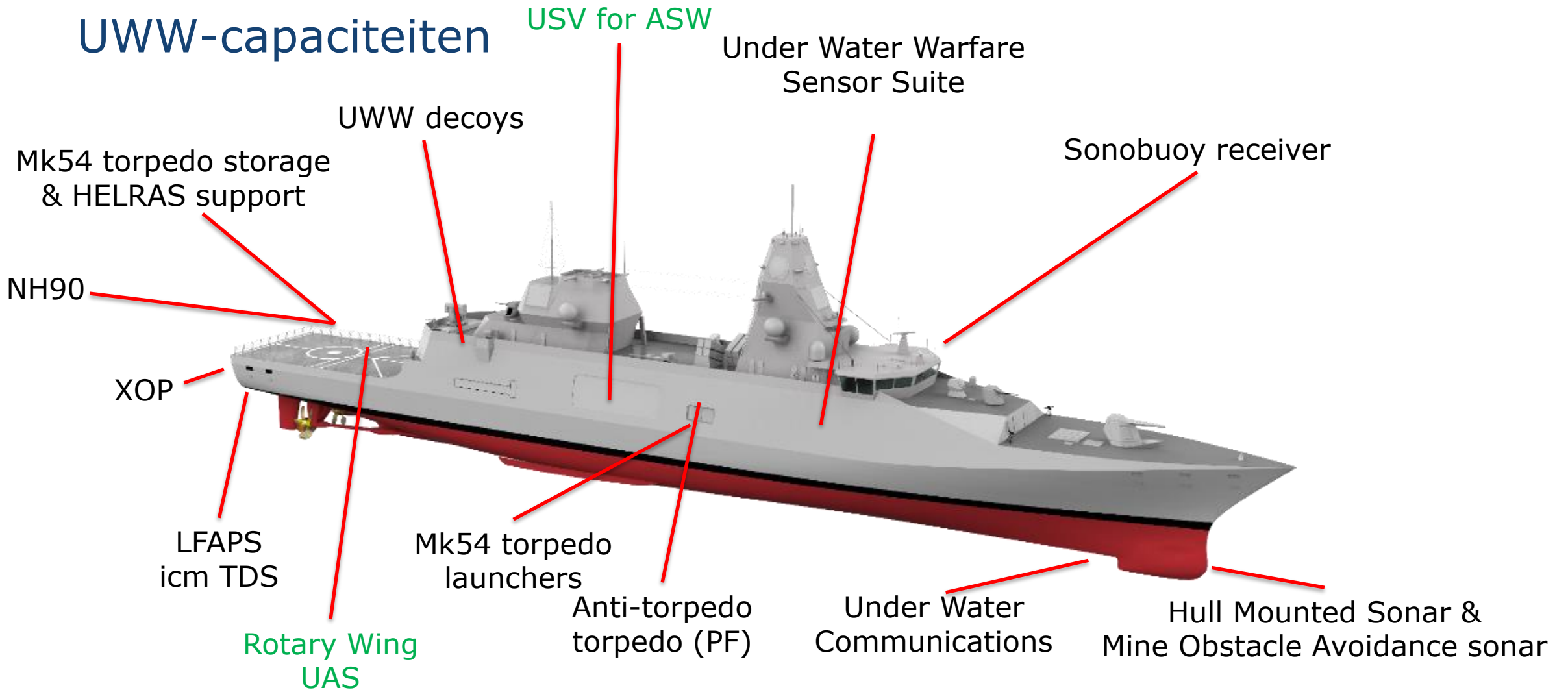
## ASW Sensor & Payload study

- 3 Research & Engineering agencies
  - Science & Literature reviews
  - Operational Research & Analysis
  - Modelling & Simulation
  - Design & Engineering
- >20 reports, memo's and slide packs





# UWW-capaciteiten



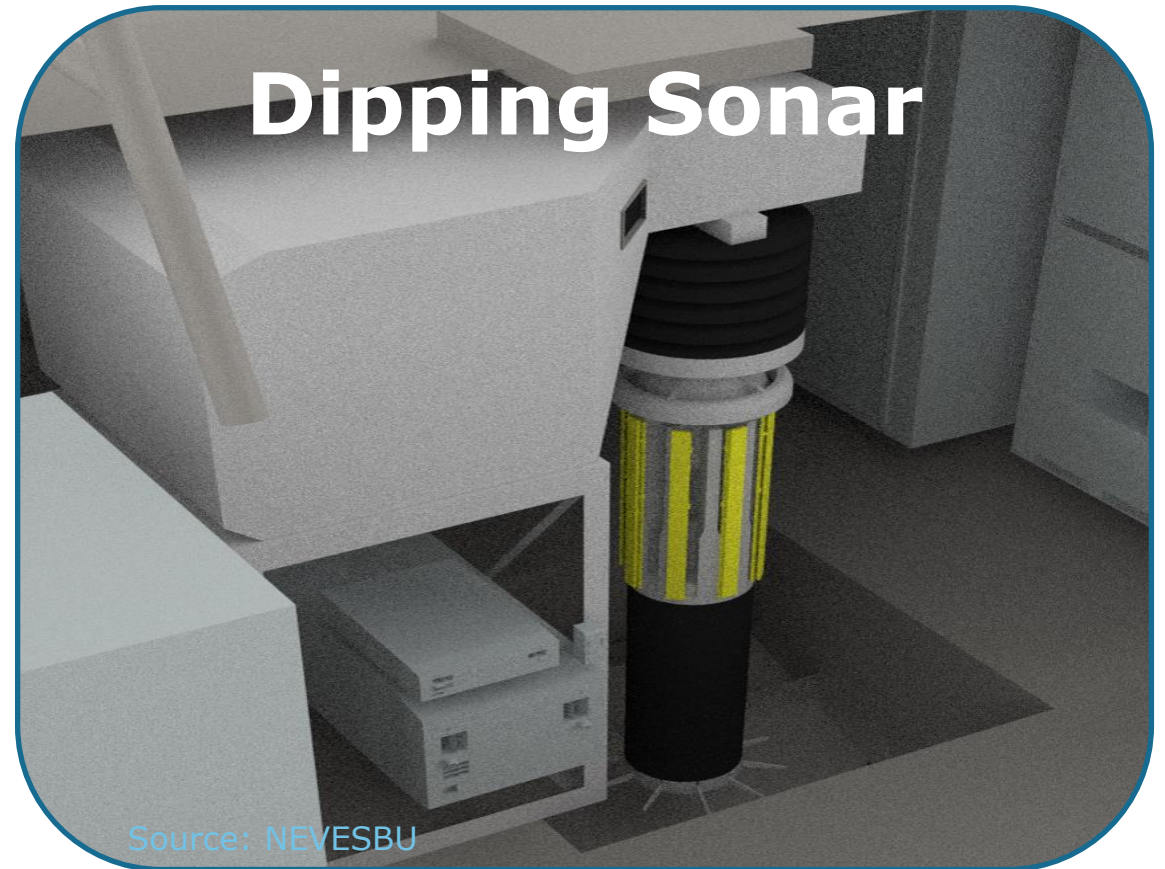


## Dipping versus Towed sonar

### Towed Sonar



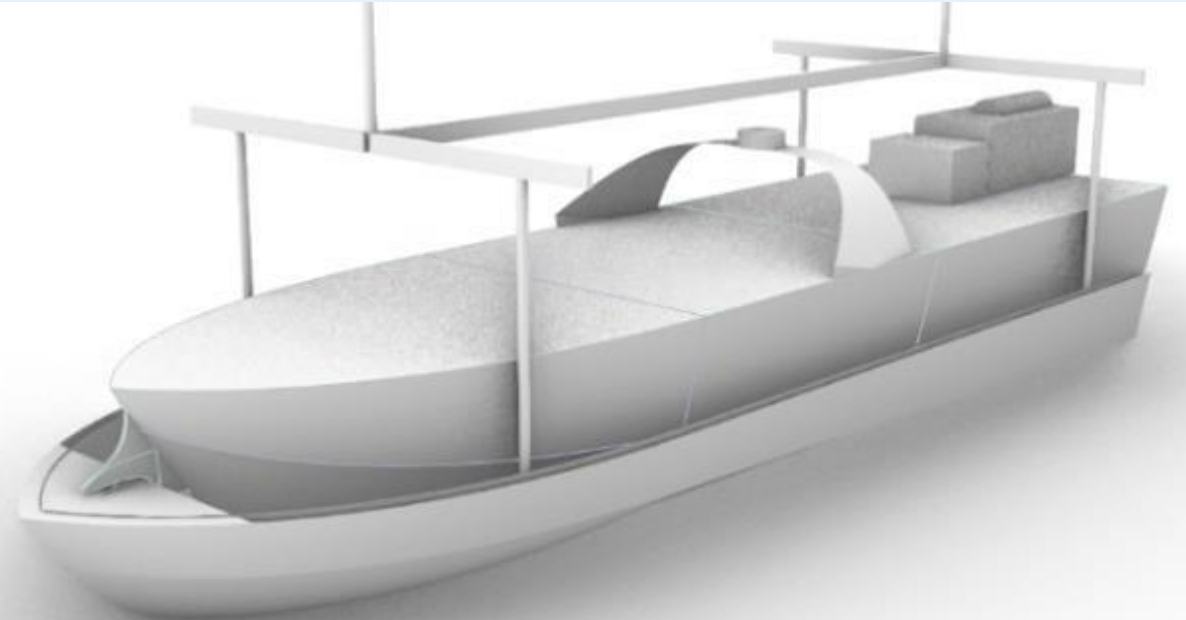
### Dipping Sonar



# STARTING POINTS

## Requirements

- The UDSB shall be able to carry and functionally operate a dipping sonar
- Minimum top speed: 20 knots
- Minimum endurance: 96 hours
- Minimum sea state: 5
- Redundancy on propulsion

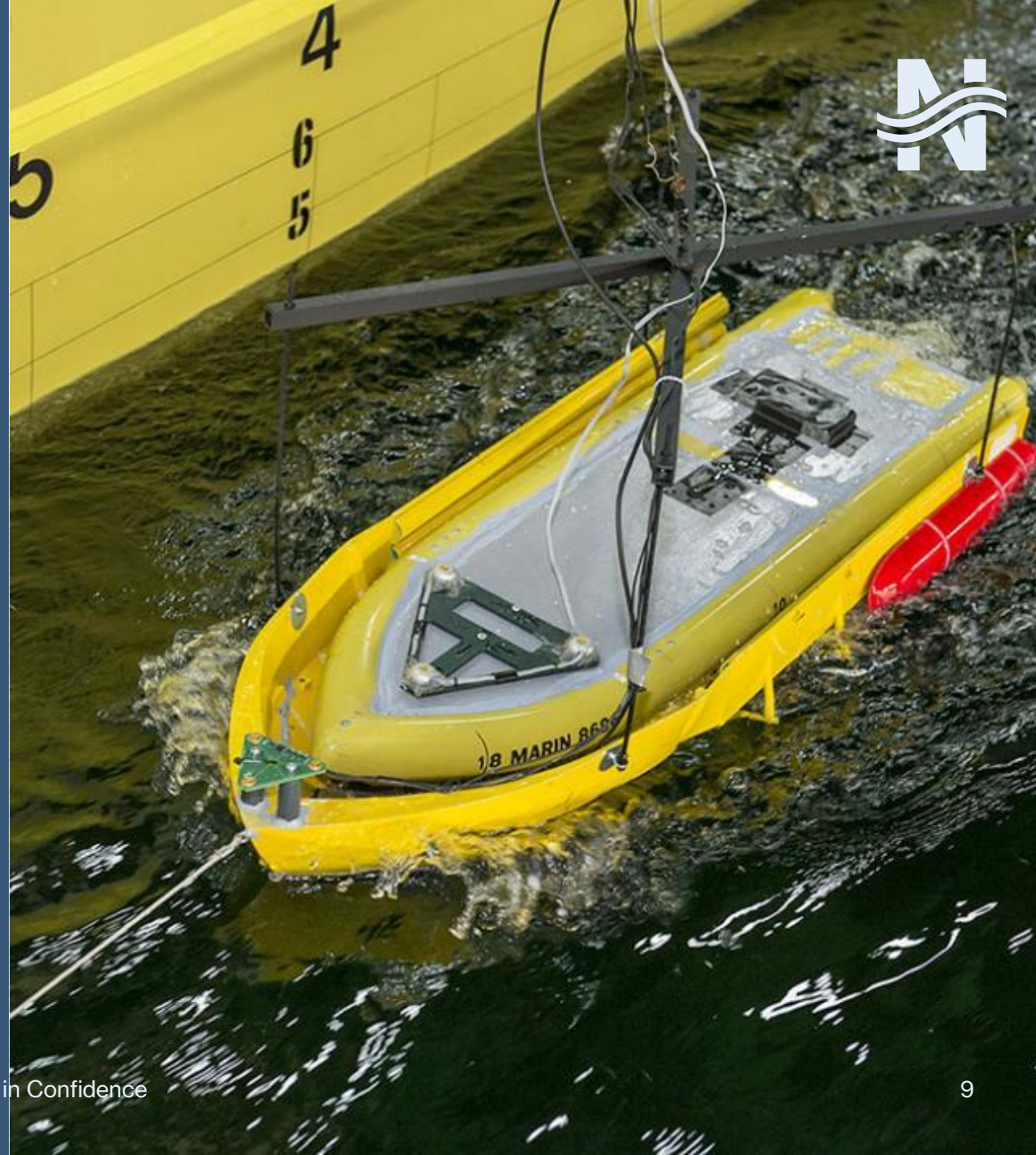




# STARTING POINTS

## ASWF integration

- Environmentals (low temperatures!)
- Maximum weight: 12 ton
- Maximum space: L: 14,4 m  
B: 5,2 m  
H: 5,7 m
- Launch and Recovery system (LARS)

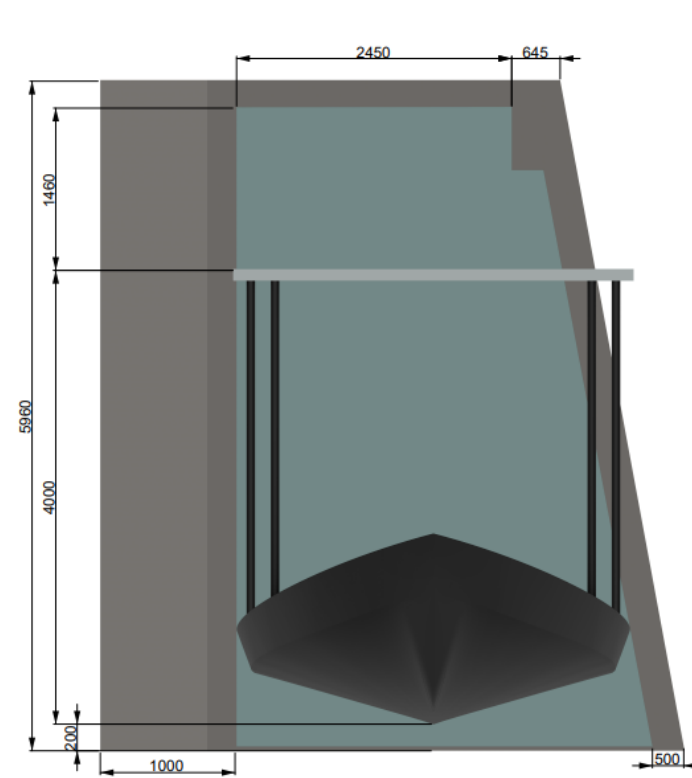


## DETAILING OF REQUIREMENTS

### Available space

- Subtractions for manoeuvring during hoisting
- 12 x 3,5 x 4,7m (LxBxH)
- Estimated weight: 2 ton
- UDSB:
  - Maximum weight: 10 ton
  - Maximum space:

L:	11,5 m
B:	2,5 m
H:	4,0 m



## DETAILING OF REQUIREMENTS

### Rules and regulations

- Goal-based regulation:
  - Lloyd's Register code for Unmanned Marine Systems
- Solution-based regulation:
  - Lloyd's Register Grey Boat Code



ShipRight  
Design and Construction

Additional Design Procedures

LR Code for Unmanned Marine Systems

February 2017



Lloyd's  
Register

Working together  
for a safer world

Grey Boat Code

A Code of Practice for  
the Safety Assurance of  
Small Boats in  
Government Service

March 2021

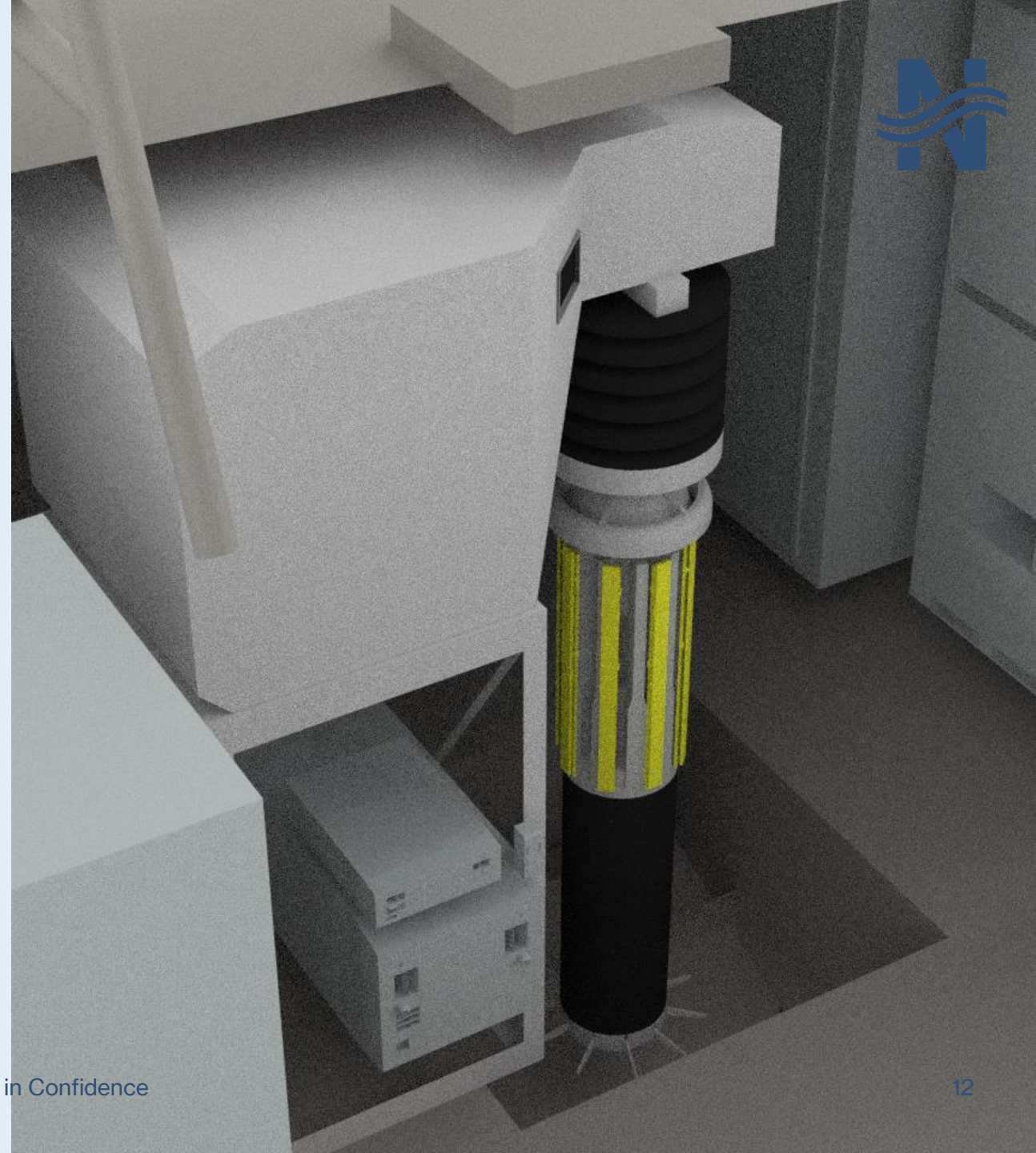


Lloyd's  
Register

## BASIS OF DESIGN

### Dipping sonar

- Moonpool
  - Sonar orientation according to supplier preference
  - Sonar is protected against environment
  - Less impact of pitch movements
- Similarity to intended use is key!



## BASIS OF DESIGN

### System identification

- Create system breakdown
- Define components for each system
  - De-icing system as part of 3000
  - Processing cabinets as part of 4100

SWBS-numbering	Systems
<b>0000</b>	UDSB
<b>1000</b>	Structure
<b>2000</b>	Propulsion and manoeuvring systems
<b>3000</b>	Electrical systems
<b>4100</b>	Command and control systems
<b>4200</b>	Navigation systems
<b>4400</b>	Communication Systems
<b>4600</b>	Underwater surveillance systems
<b>5000</b>	Auxiliary systems
<b>5550</b>	Fire extinguishing systems

## BASIS OF DESIGN

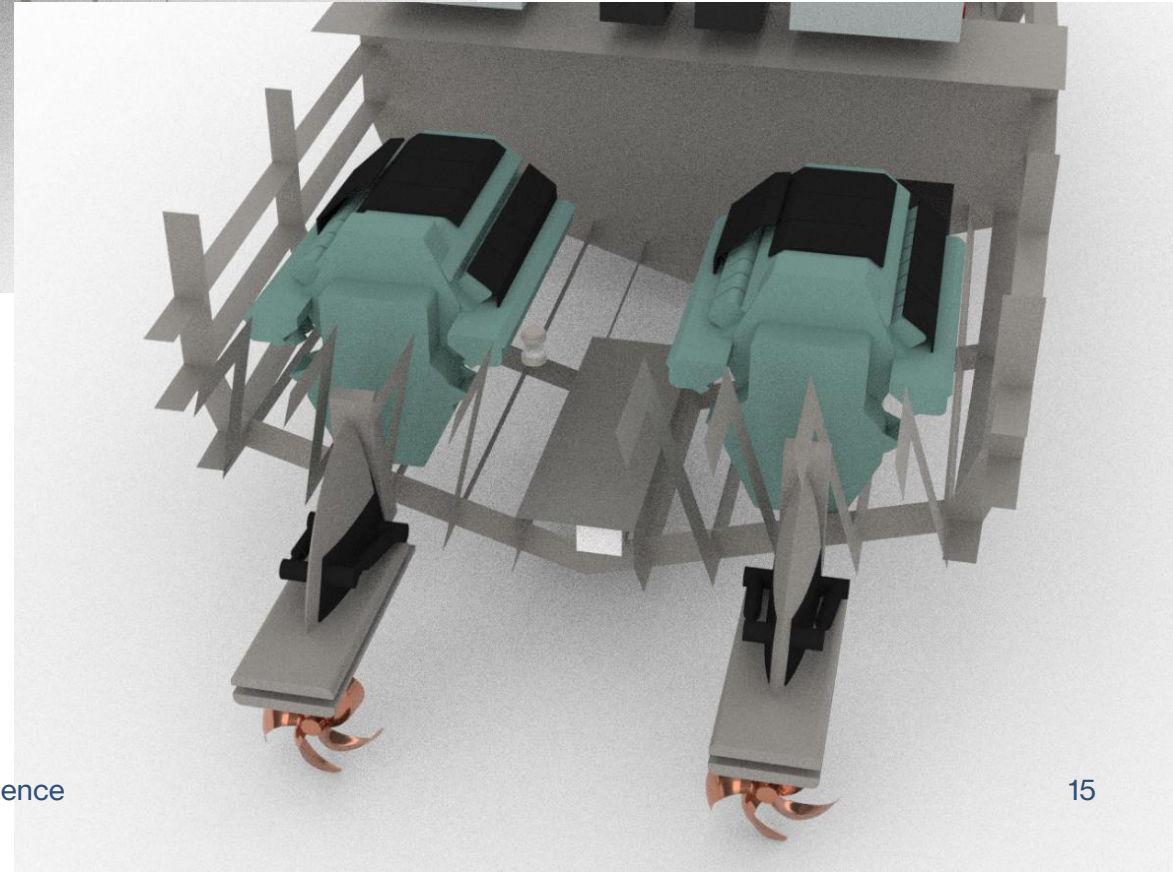
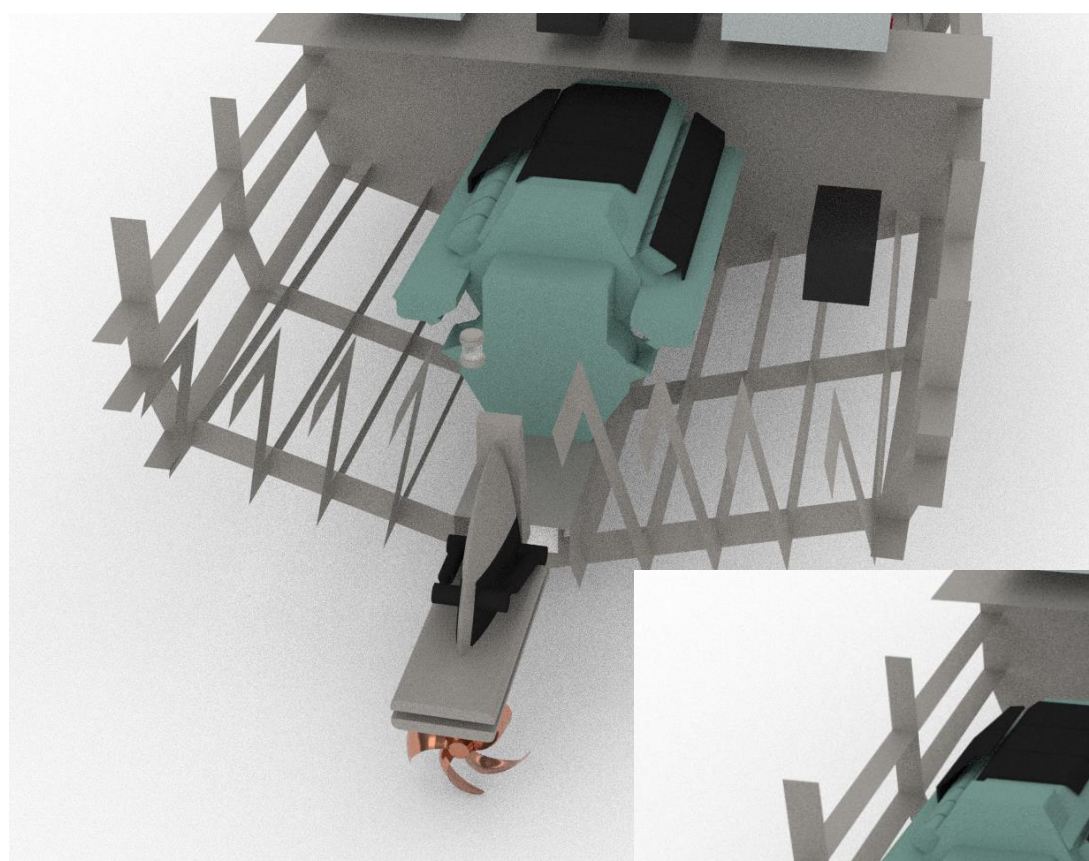
### Hull shape

- Hull optimization not part of concept design
- Reference hull shape for fast results
- Scaled to meet dimension criteria



# ENGINE LAYOUT

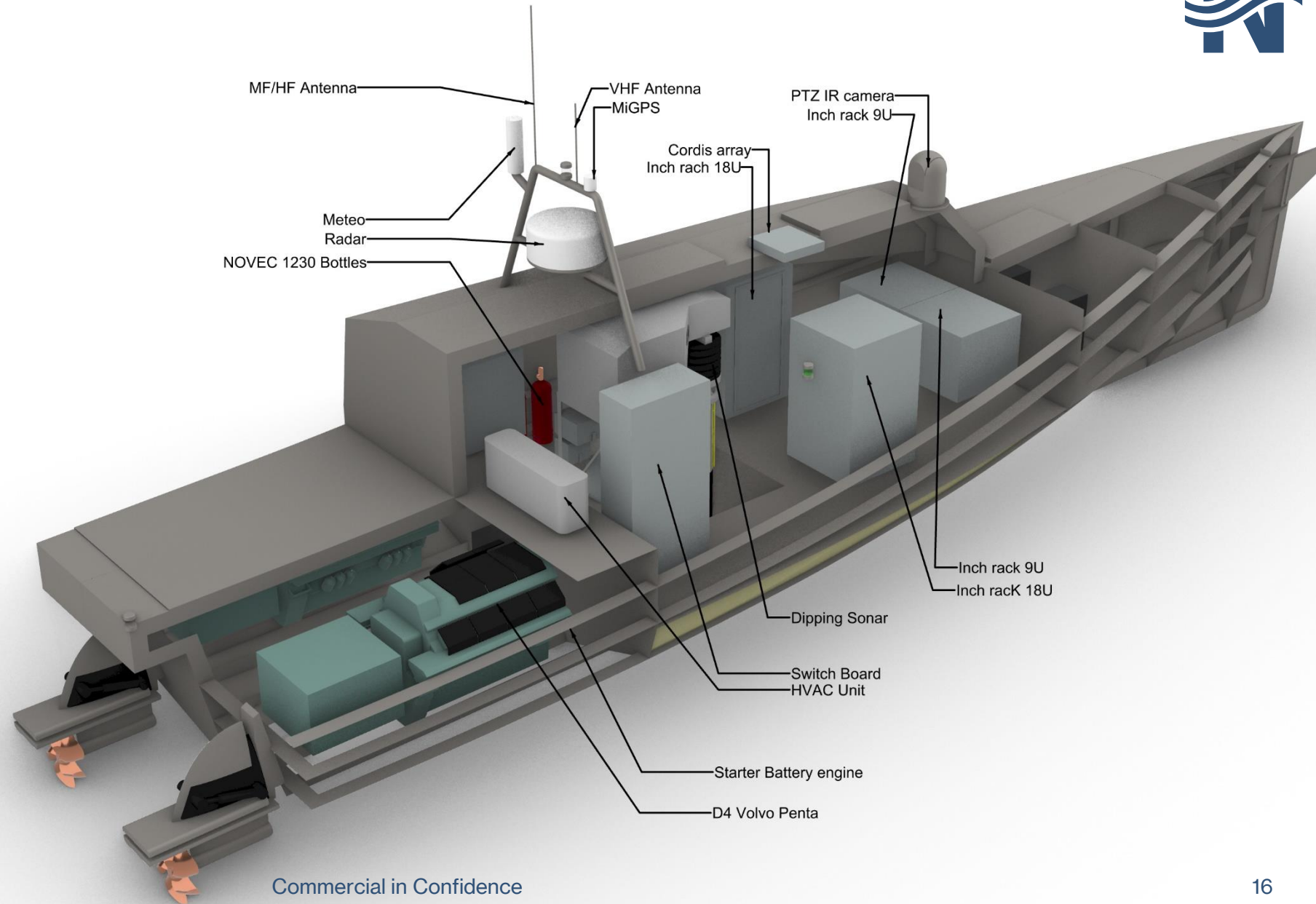
- Power take-off
- Limited maintenance space
- Aft deck removable
- Redundancy is required, but limited possible



# FINAL CONCEPT

## Principals

- Length = 11,2 m
- Breadth = 2,5 m
- Height = 4,3 m mast up  
2,6 m mast down
- Displacement = 9,2 ton
- Speed = 20 knots







## Sonar wet-end motion & Motion Compensation

Horizontal & vertical motion influence sonar performance

- Horizontal drift influences processing
  - Dynamic Positioning required?
- Doppler spread
  - Accept it
  - Lower stiffness hoist cable
  - Heave compensation
  - Advance processing
  - Combination of above





## Way ahead?

Continue design  
USV

Automation  
detect,  
classification &  
tracking

ASWF & USV  
Teaming

Mission  
Autonomy

Launch &  
Recovery

USV – Sonar  
interaction



## Takeaways

Concept design takaways:

- 12 meter frigate launched USV with active sonar is feasible
- Challenging CONOPS – 20 kts - SS5 North Atlantic is doable
- But, more engineering required for first of class