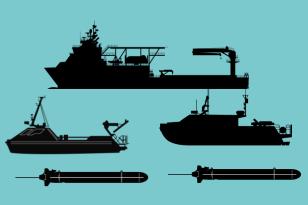
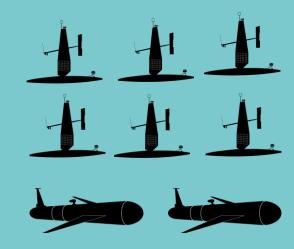
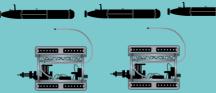


The problem statement



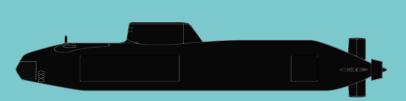




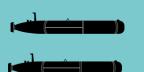


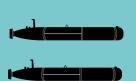


















Existing autonomy levels

Level 4
Fully autonomous

Level 3

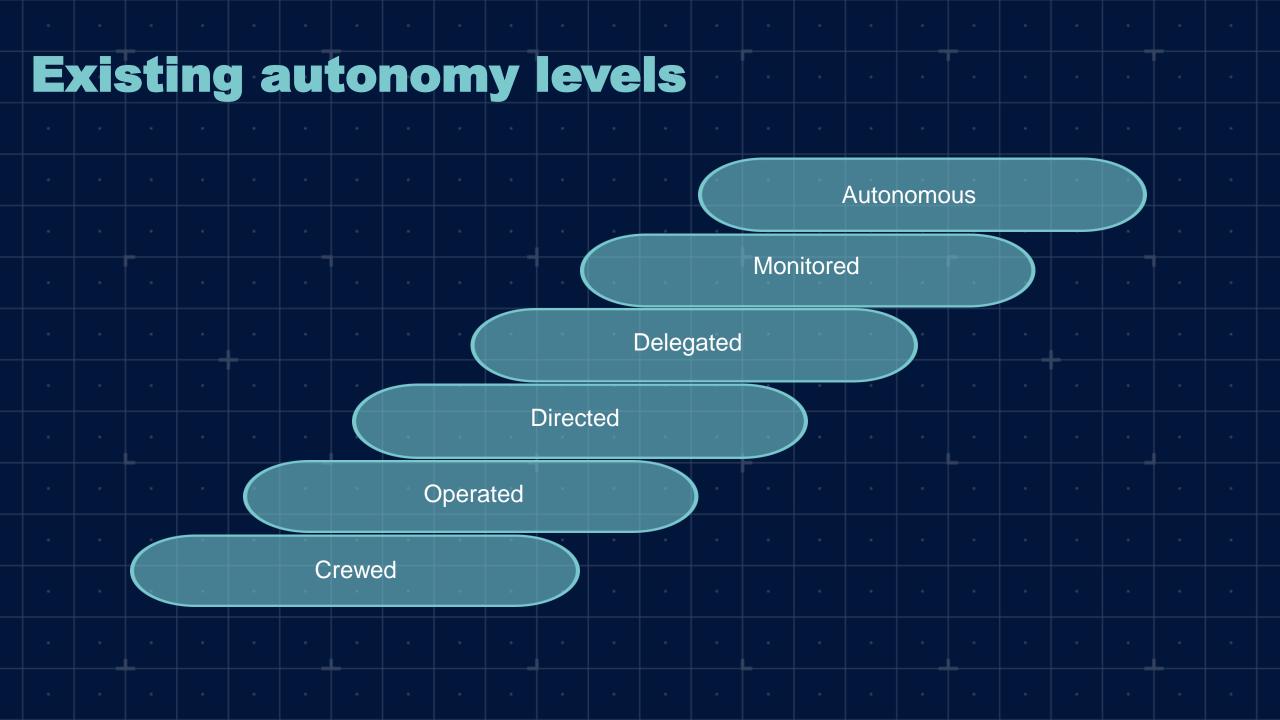
Remote controlled without seafarers onboard

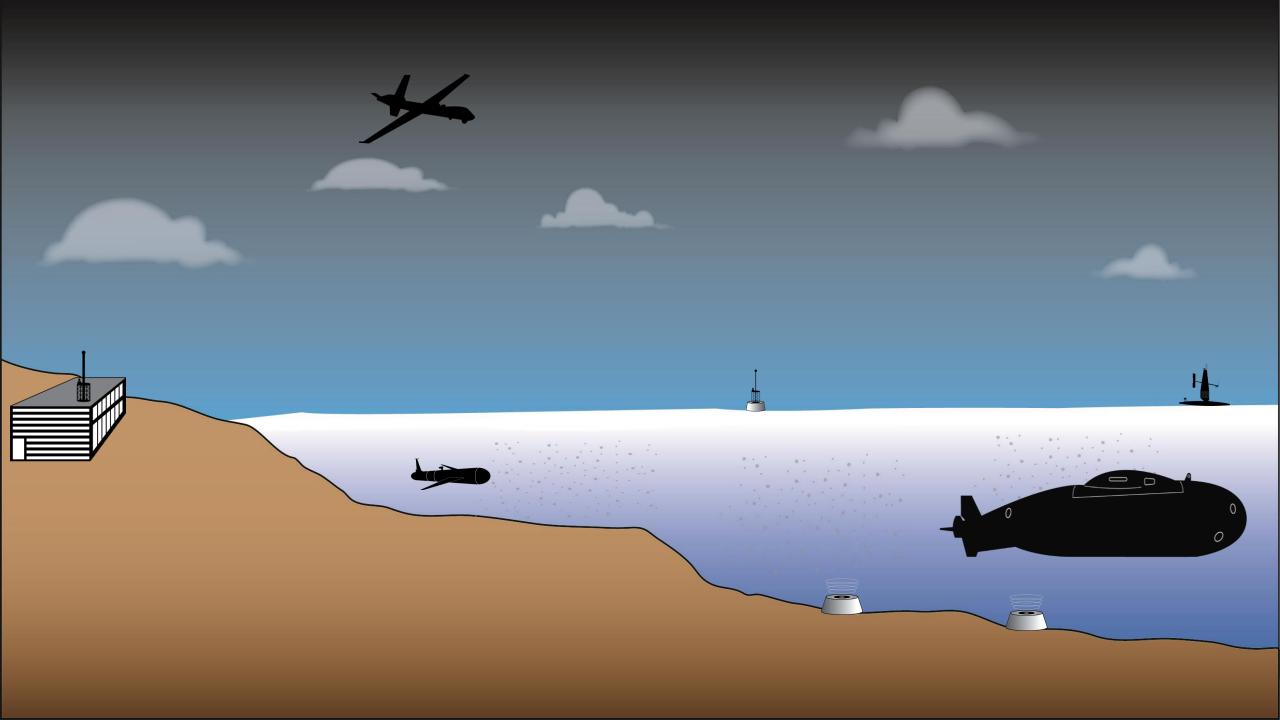
Level 2

Remote controlled with seafarers onboard

Level 1

Seafarers onboard and some automation





Military operator oversight and automated decision-making levels (MODL)

Automated decision-making

Autonomous

Delegated

Directed

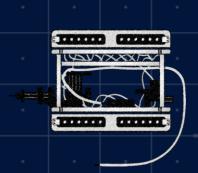
None















Onboard

Close Offboard

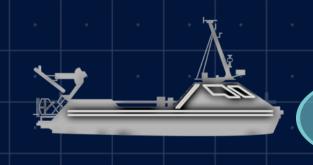
Loose Offboard

None

Comparisons



Human/machine teaming



Level 4
Fully autonomous



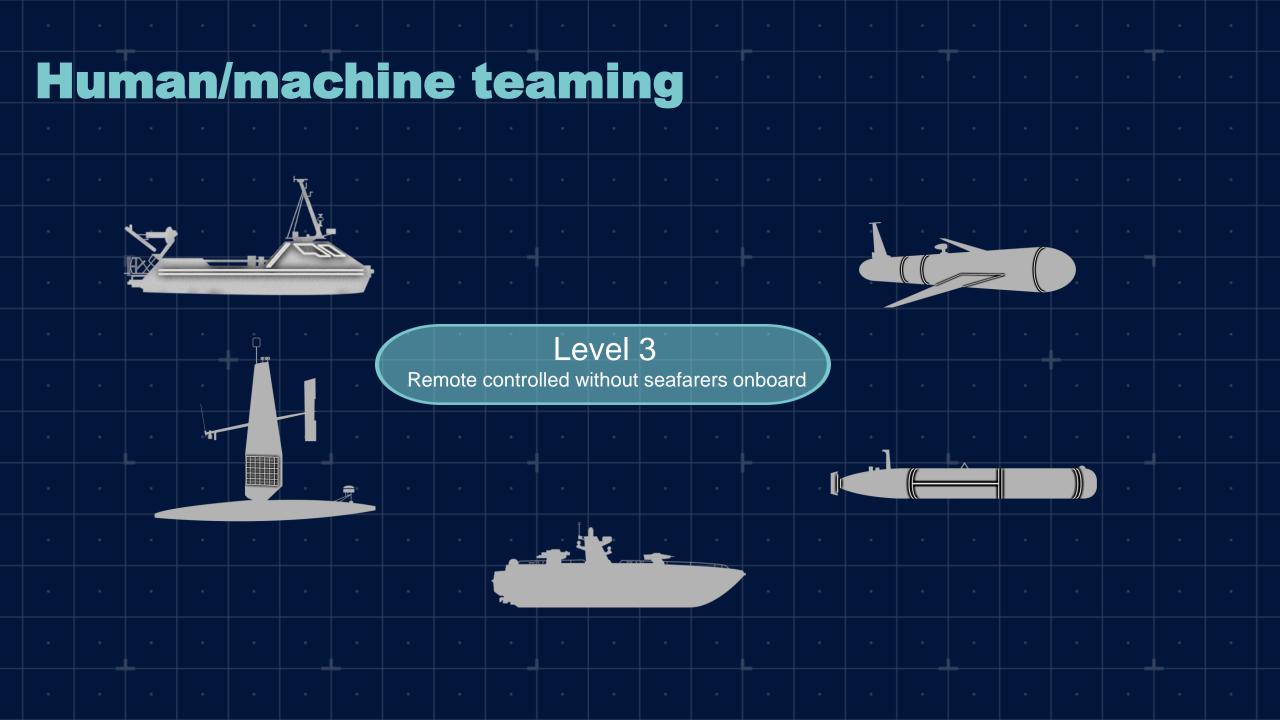
Level 3
Remote controlled without seafarers onboard

Level 2

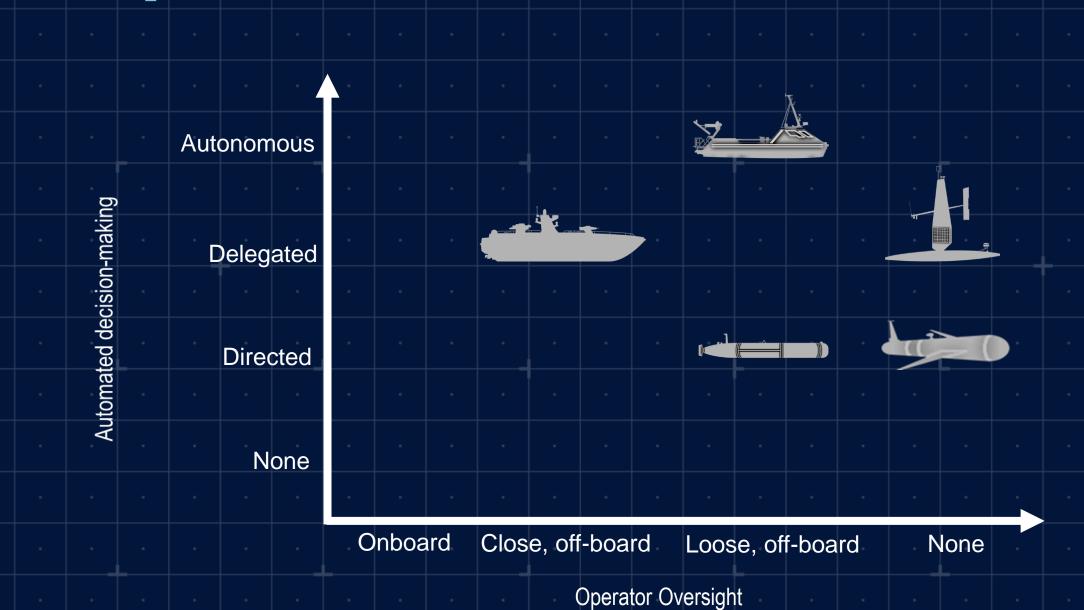
Remote controlled with seafarers onboard

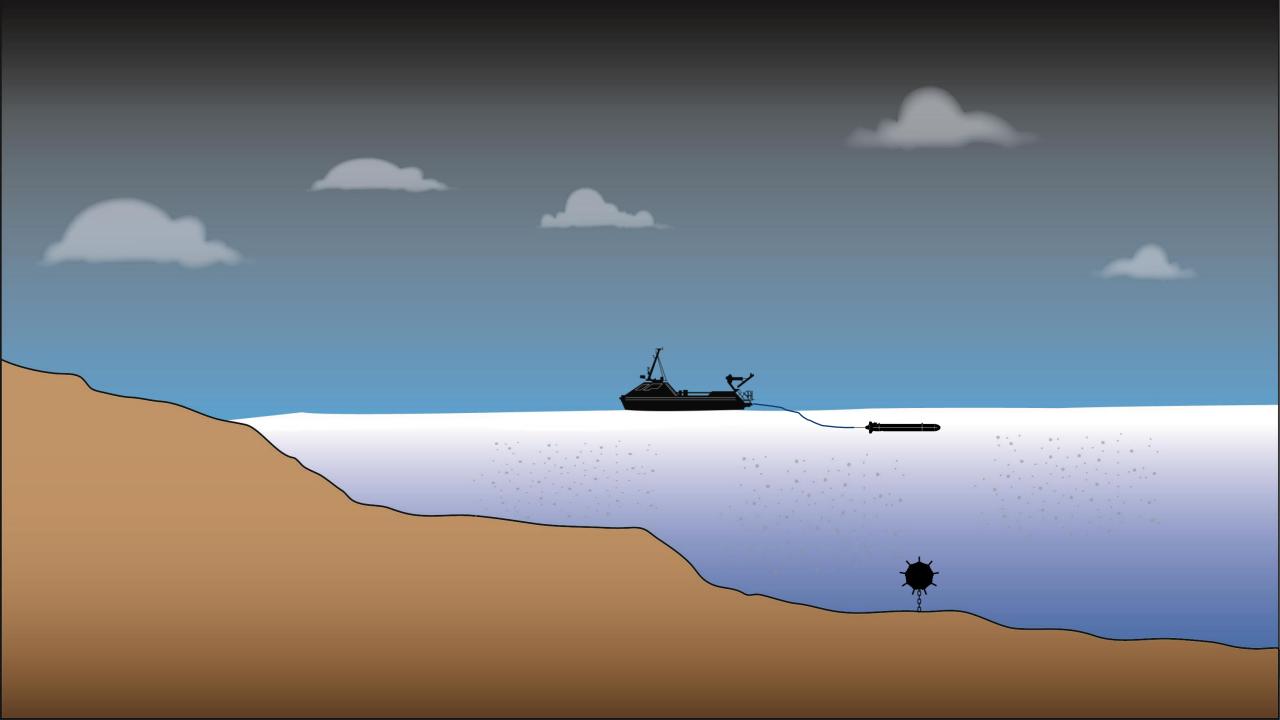
Level 1

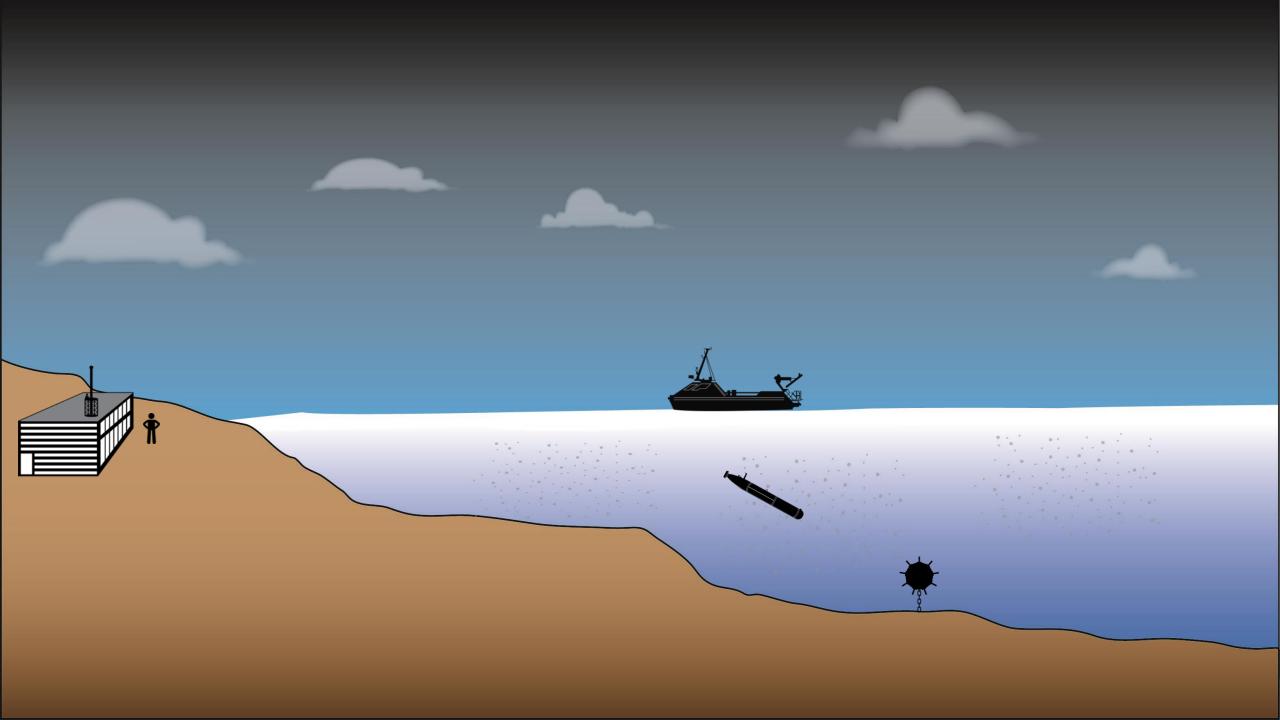
Seafarers onboard and some automation

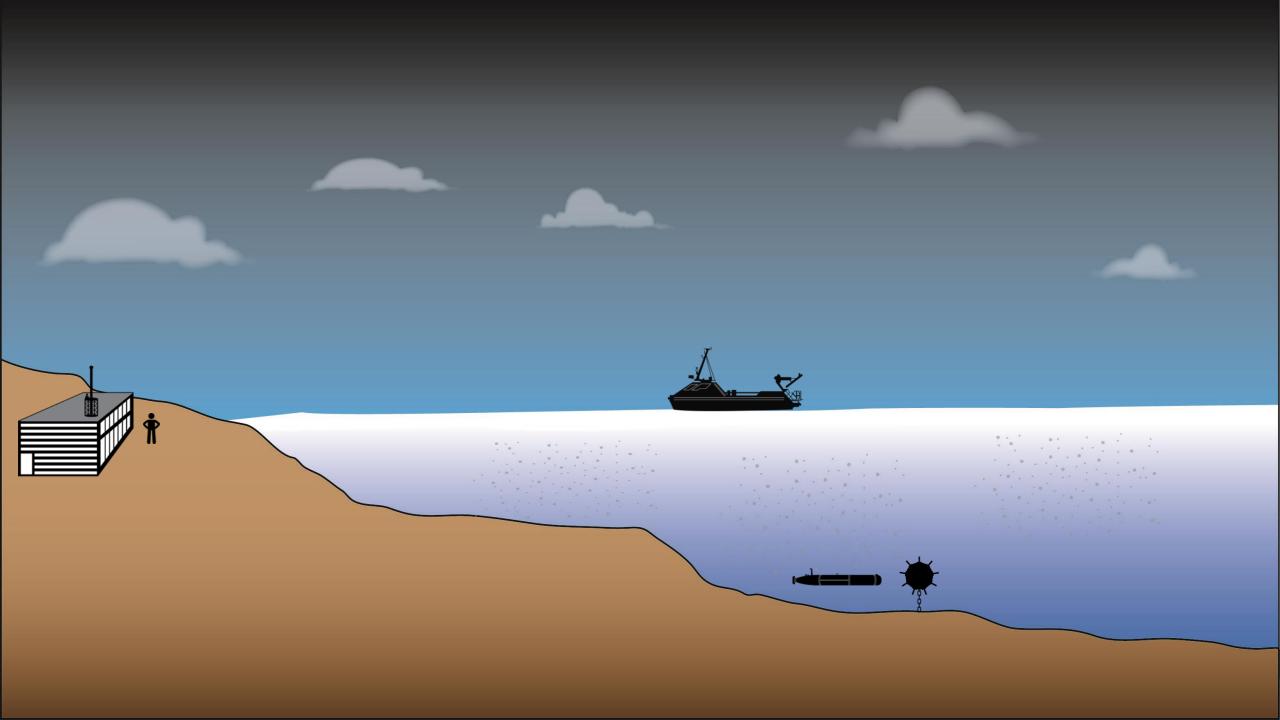


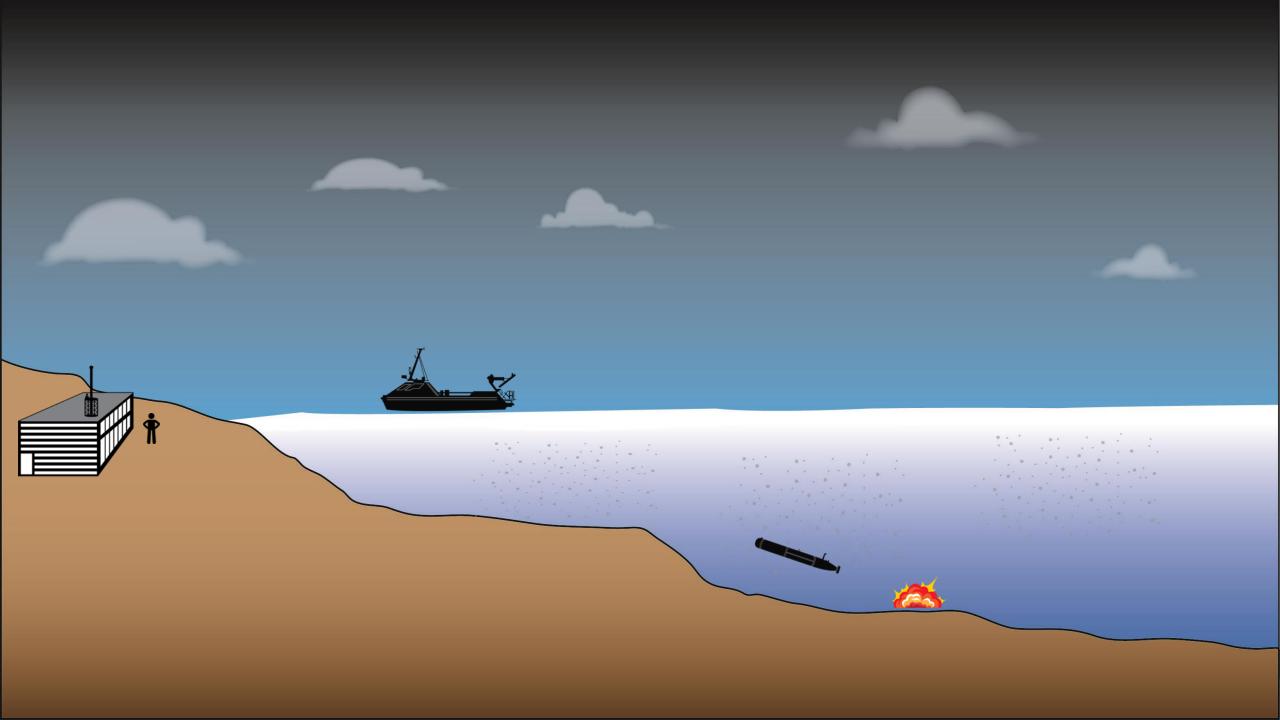
Comparisons











Worked Example

Level 4
Fully autonomous



Level 3

Remote controlled without seafarers onboard

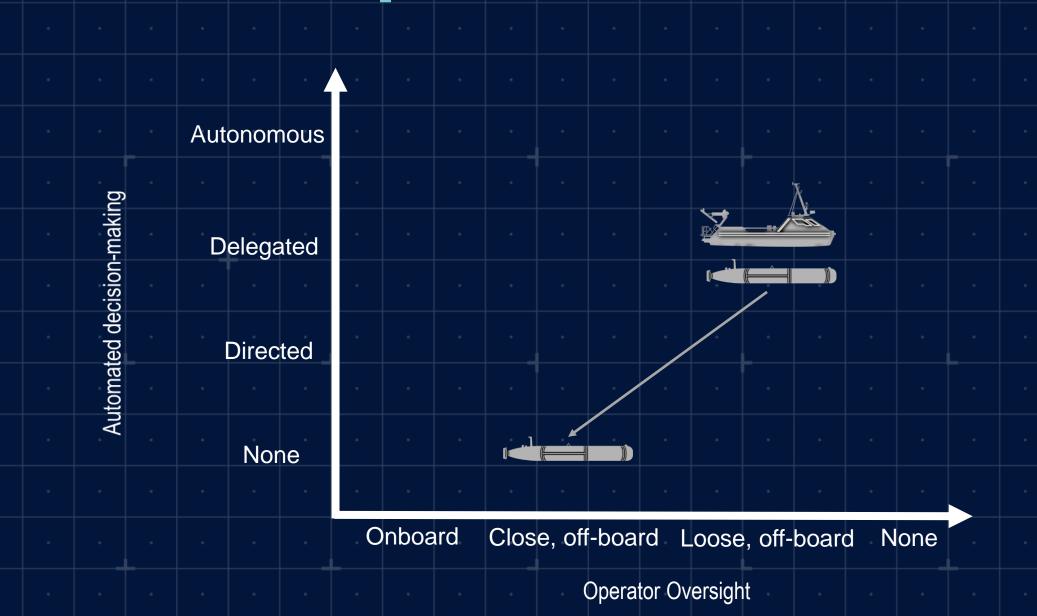
Level 2

Remote controlled with seafarers onboard

Level 1

Seafarers onboard and some automation

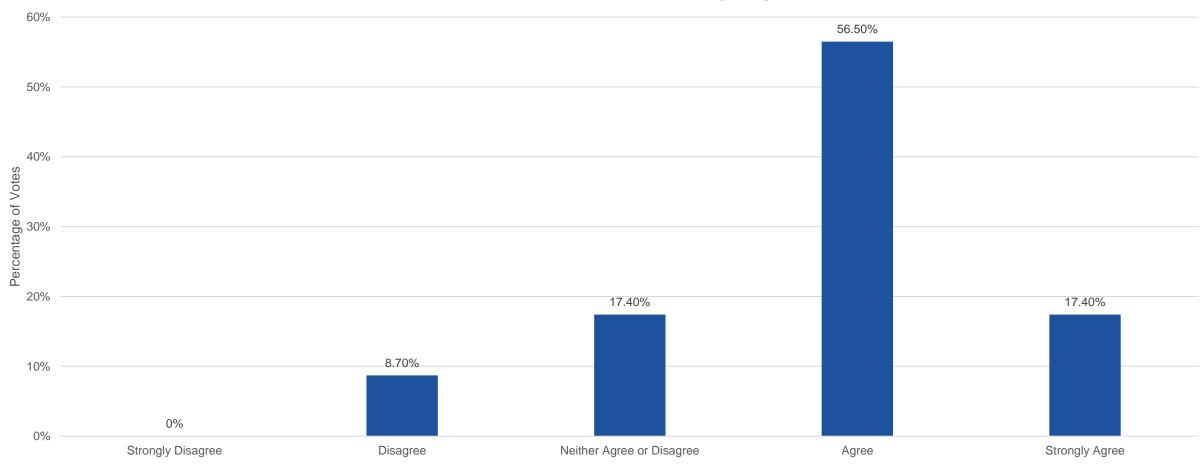
Worked Example

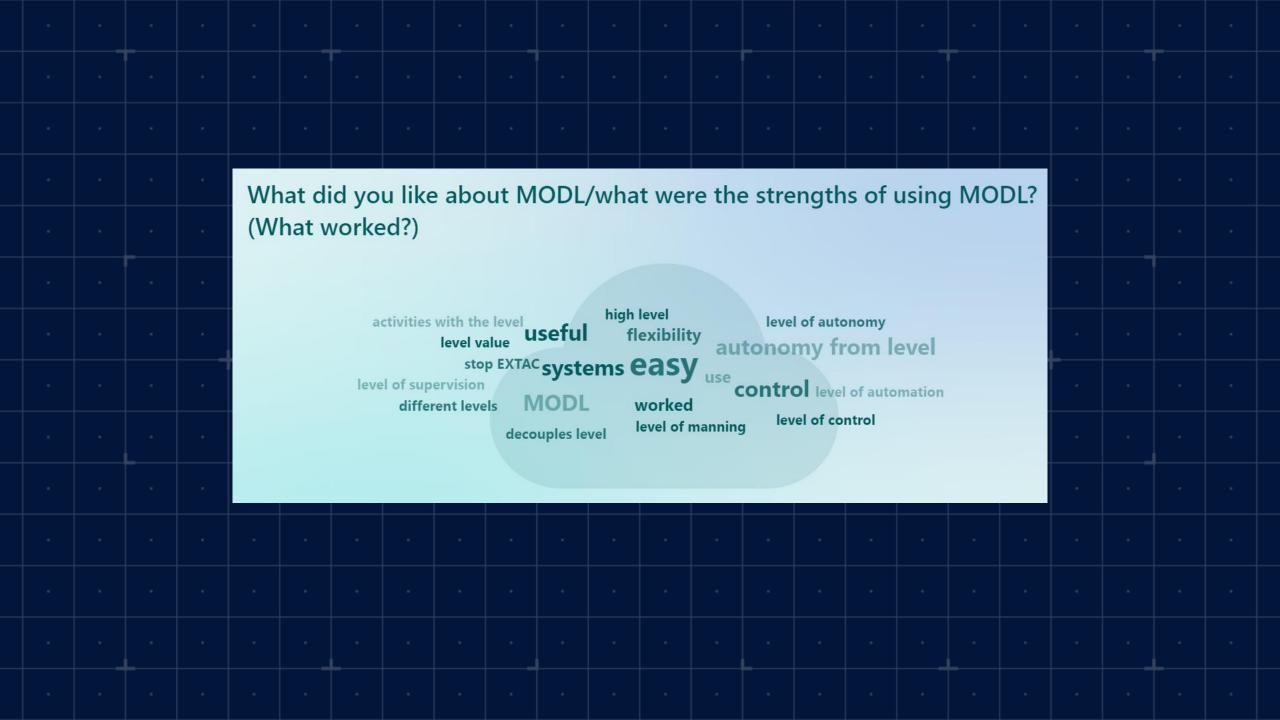




Results

Question 1 - I would use MODL frequently.







Operational experimentation insights

Standardisation

Complexity

Clarity





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Staff Officer Submarine Littoral Warfare

Operational Advantage Centre (Maritime Warfare) HMS Collingwood, Fareham