

https://www.designengineeringexpo.co.uk/workshop-agenda-2022



# MASTERCLASS IN DIGITAL SENSORS

Thursday 9th June, 2022 @ 11:00 NEC Birmingham, GB Gopi Patel – Field Applications Engineer EMC | Power | IoT

WURTH ELEKTRONIK MORE THAN YOU EXPECT

## **Masterclass in Digital Sensor**

Agenda:

- Brief history and evolution of sensors
- Construction of mems sensor
  - Temperature, Humidity, Pressure, Accelerometer
- Electronic interface
  - I2C, SPI
  - Firmware
- Design recommendations
  - Schematic, PCB layout, EMI filtering
- Take home
  - Eval board, CAD library, SDK, software examples
  - Surprise, Q&A and Thank you





# <u>HISTORY AND EVOLUTION</u> <u>OF SENSORS</u>



## History and evolution of sensors

### Sensors that were borne more than a century ago:

Mercury, bimetal strip, strain-gauge, spring coils etc.

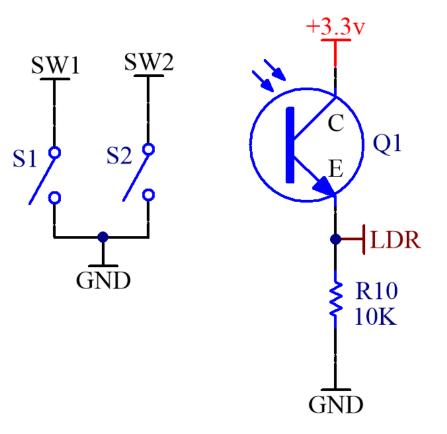
### Sensors that dominates todays market:

Voltage, current, pulse, click, swipe, pressure, touch, light, temperature, occupancy, movement, angle, tilt, acceleration, rotation, free-fall, location, altitude, flow, gas, liquid, distance, motion, IR, PIR, radar, Lidar, Sonar, acoustic, microwave ...

These are capacitive, resistive, semiconductor or MEMS

### **Futuristic sensors:**

ToF, AoA, AoD, VOC, CO<sub>2</sub>, CO, NO<sub>2</sub>, SO<sub>2</sub>, AI, VR, AR, Machine learning...



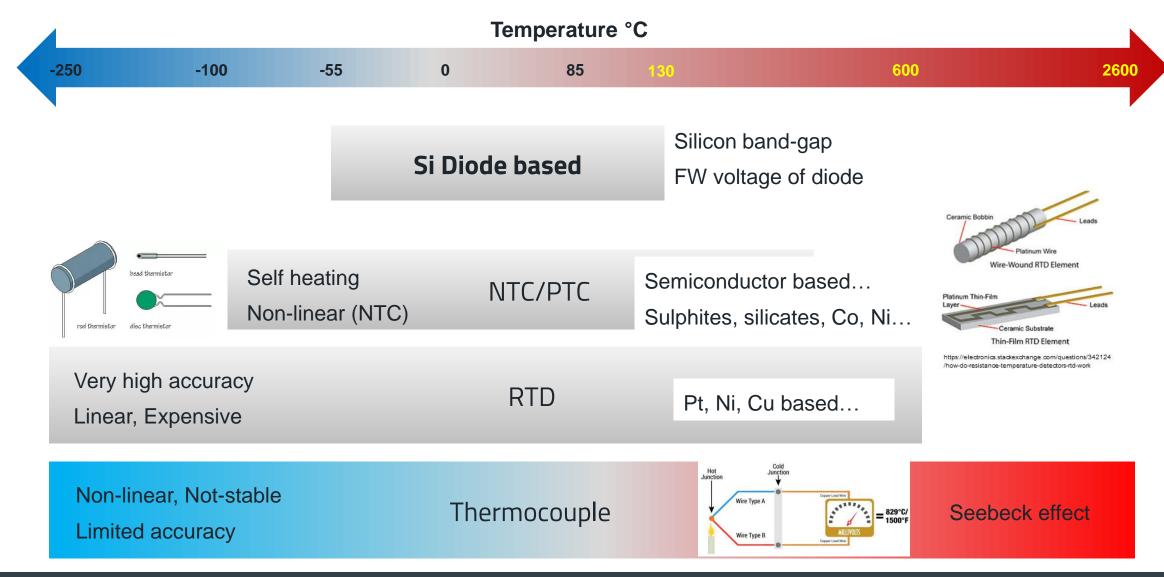


# **TEMPERATURE SENSOR**



https://www.we-online.com/catalog/en/WSEN-EVAL\_TIDS

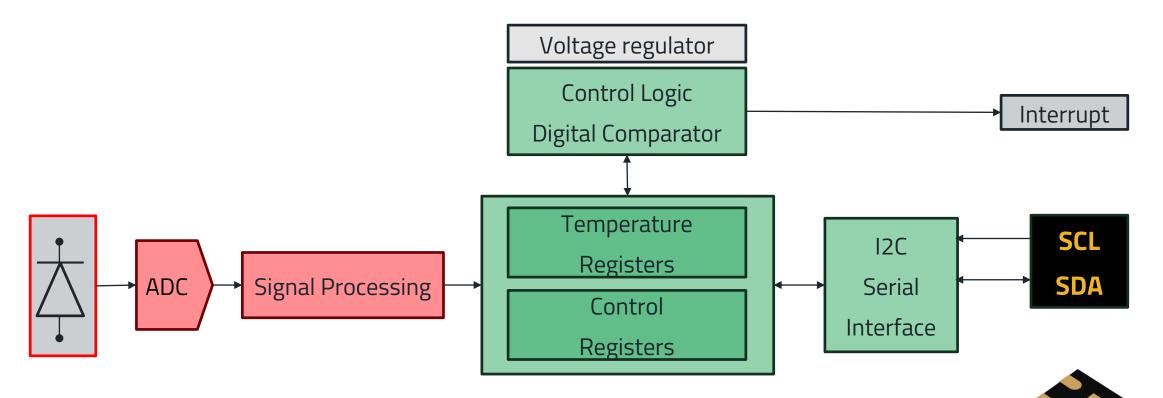
## **Types of Temperature Sensors**



## **Temperature Sensor Comparison Table:**

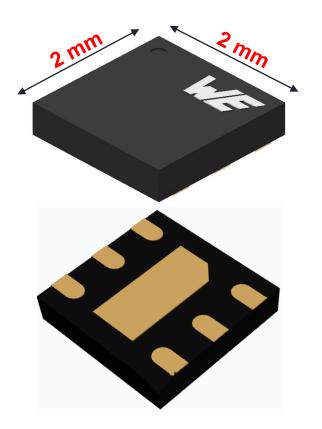
	Votrage + Temperature	Gesistance	Gesitance Temperature	Berto Ministry Control of the second
	Thermocouple	RTD	Thermistor	Semiconductor IC based
Measurement range	-250 °C to 2500 °C	-250 °C to 700 °C	-100 °C to 250°C	-55°C to 150°C
Accuracy	Average (require CJC)	Highest	Average	High
Sensitivity	Low-average	Average	High	High
Linearity	Average	Good	Low	Highest
Peripheral Circuits/Calibration	CJC; Amplifier; Scaling	Resistance correction; Scaling	Scaling	No
Footprint	Large	Medium	Small	Smallest
Price	Moderate	Very high	Low	Low

## WSEN-TIDS: Block Diagram



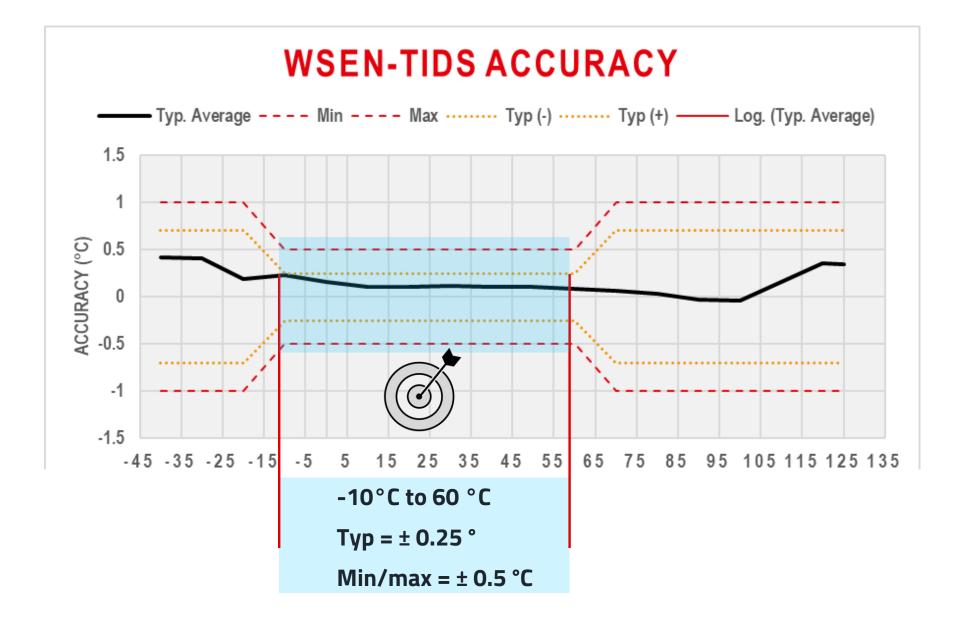
- ✓ Si based diode (BJT) + digital logic  $\rightarrow$  Single ASIC
- ✓ Factory calibrated output
- ✓ No peripharal circuits

## **TIDS - Temperature Sensor: Technical Features**



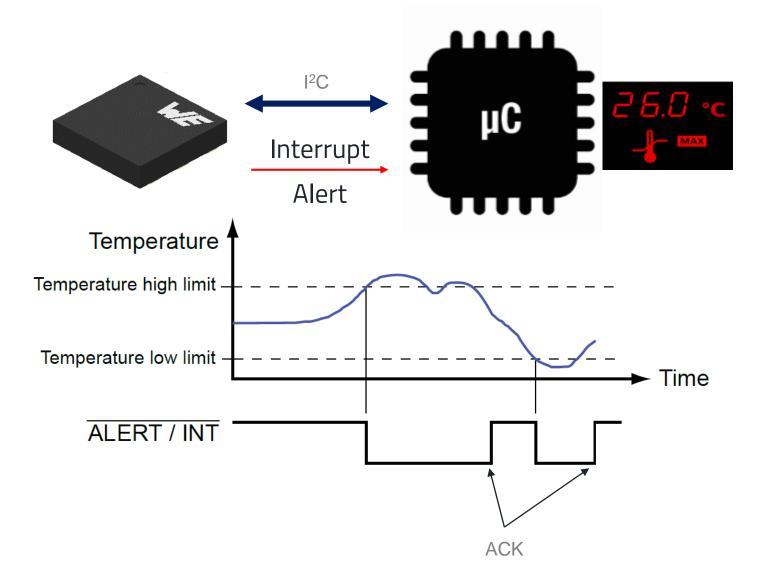
- ✓ Compact 2 x 2 x 0.5 mm package
- Temperature Range: -40° to +125°C
- Accuracy: ±0.25°C (typ.) / ±0.5°C (max)
- 16 bit Output resolution
- ✓ Low voltage: 1.5 to 3.3 Volts
- ✓ Ultra-Low Current Consumption: 1.75 µA / 0.6 µA
- Exposed pad at the bottom
- Fully calibrated during production
- Most importantly in stock





## TIDS to MCU Interface:

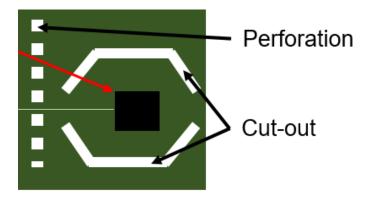
- ✓ Digital I2C serial interface
- ✓ Two selectable address
- ✓ Single conversion
- ✓ Continuous o/p
- ✓ 25 to 200 Hz ODR
- ✓ 40ms to 5ms refresh rate
- ✓ Interrupt output
  - ✓ Temperature high
  - ✓ Temperature



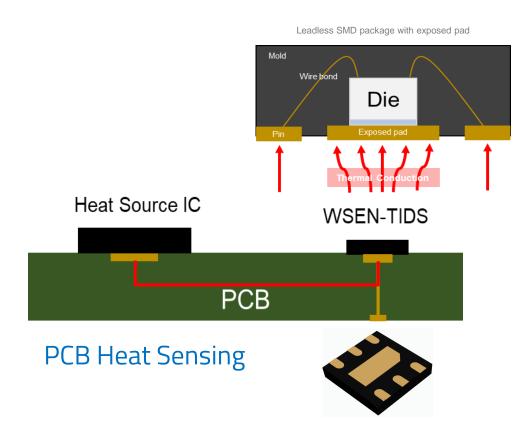


## <u>TIDS - Temperature Sensor: Structure + Applications:</u>

- ✓ Automatic Fan control
- ✓ Highly accurate PCB temperature monitoring...
- ✓ Highly accurate air temperature measurement
- ✓ Constant Temperature crystal Oscillators

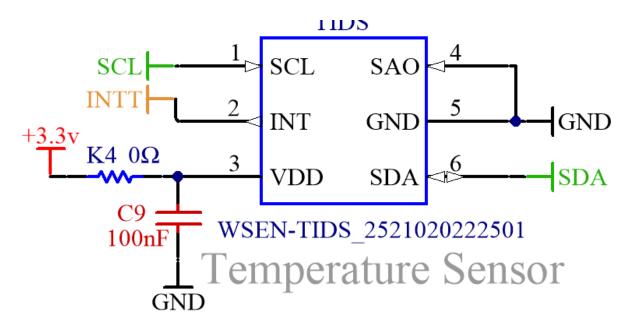


**Ambient Temperature Sensing** 





## <u>TIDS – Temperature Sensor: Schematic and PCB Recommendations:</u>



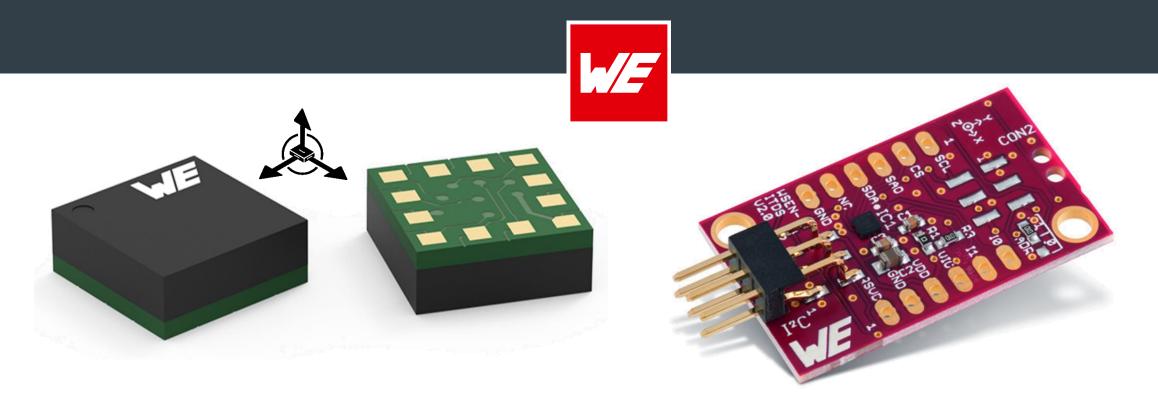
- SAO may be used to alter I2C address
- K4 OΩ link can be used to measure sensor current
- K4 could also be replaced with ferrite bead
- Decoupling capacitor is recommended for EMI (C9)
- I2C may require pull-up resistors ~ 10KΩ

### Firmware Example:

float temperature = sensor.read\_temperature();
Serial.print(temperature);

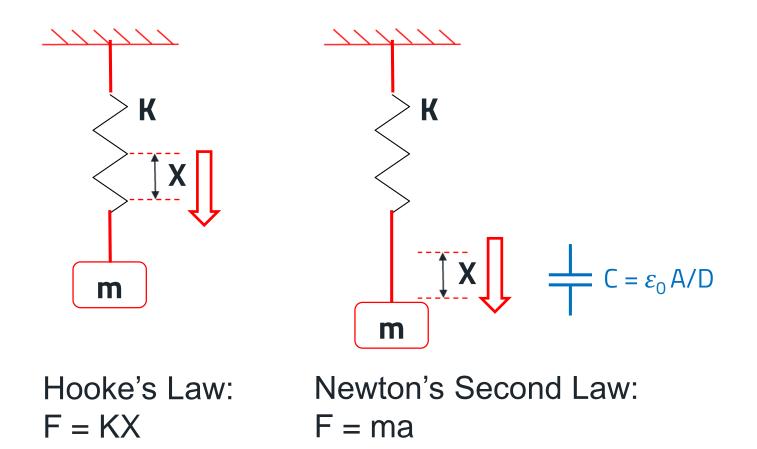


# **ACCELERATION SENSOR**



https://www.we-online.com/catalog/en/WSEN-EVAL\_ITDS

## **Basic Principle of Acceleration Sensor:**



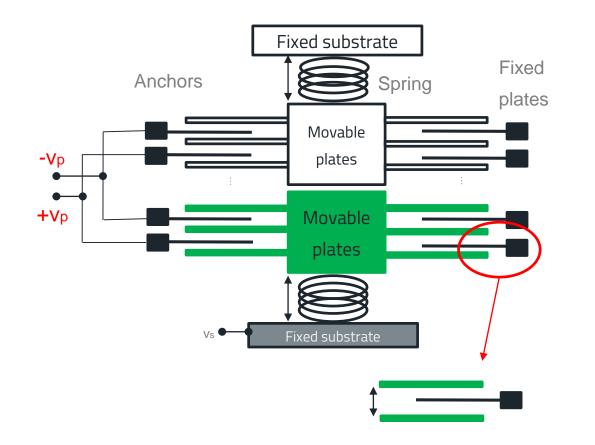
F = KXF = ma

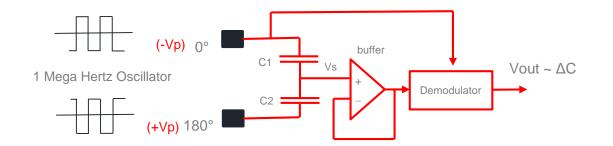
So, acceleration: A = KX/M A = change in capacitance

K = Tensile (spring) constantX = Displacement of springm = mass of the objecta = acceleration

ε<sub>0</sub> = Dielectric constant
 A = Area of the capacitive plates
 D = distance between plates

## **Basic Principle of MEMS Sensor:**

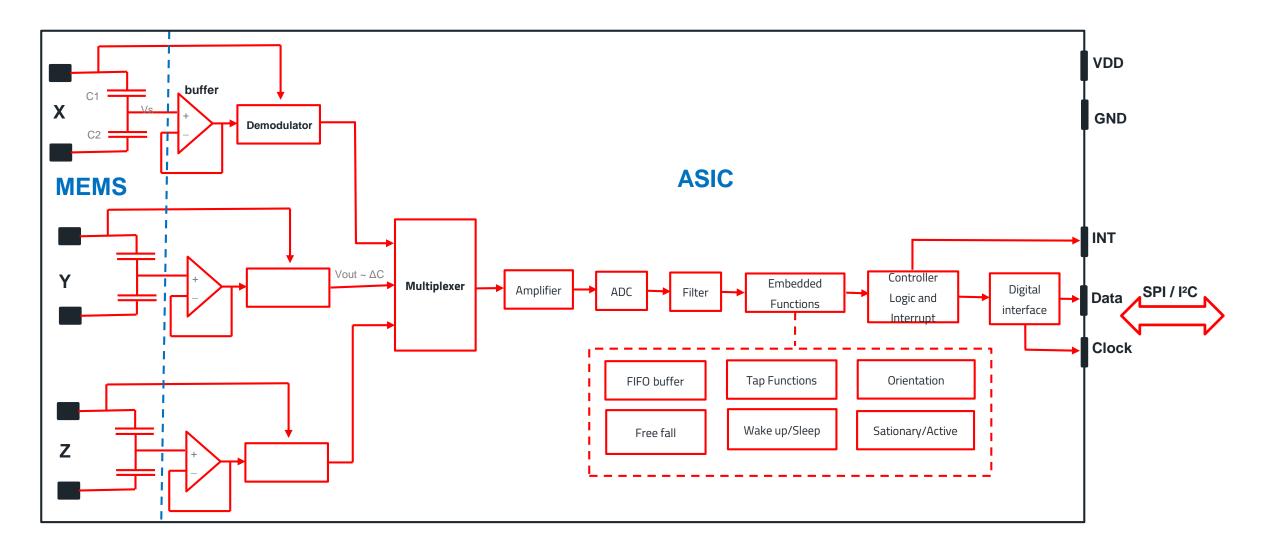




MEMS: Micro-Electro Mechanical System

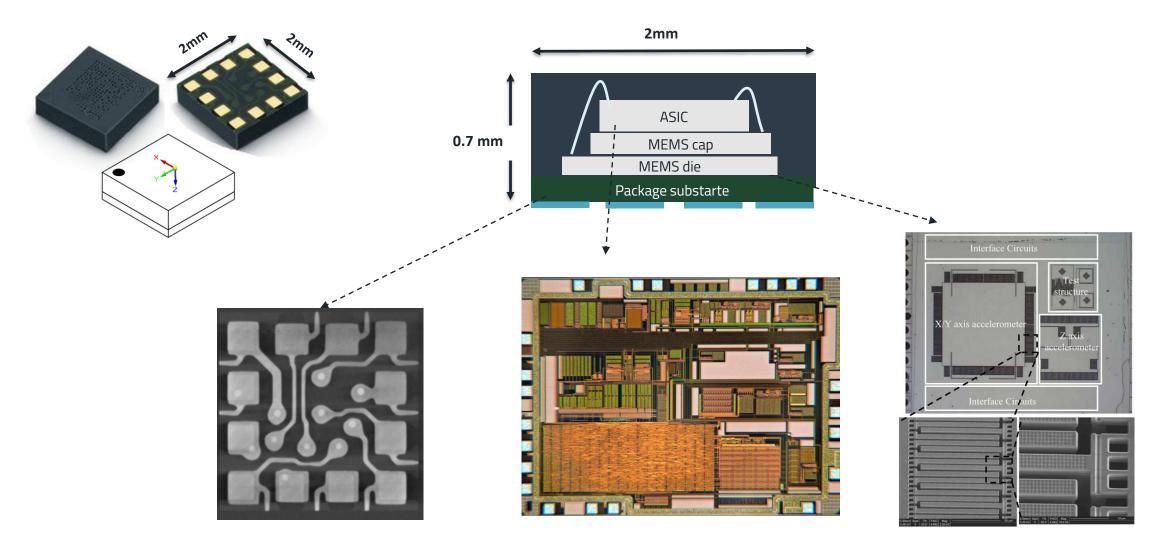


## ITDS – 3 axis acceleration sensor (accelerometer)





## <u>MEMS – capacitive acceleration sensor: internal structure</u>

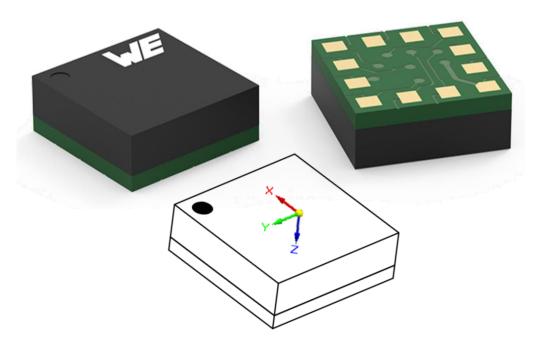


https://www.ims.fraunhofer.de/de/Geschaeftsfelder/Biohybrid-Systems/Anwendungen/Multisensor-System.html

Sun, Hongzhi, et al. "A Low-Power Low-Noise Dual-Chopper Amplifier for Capacitive CMOS-MEMS Accelerometers." *IEEE Sensors Journal*, vol. 11, no. 4, 2011, pp. 925–933., Ioi:10.1109/jsen.2010.2064296



## ITDS – Technical Features of Accelerometer

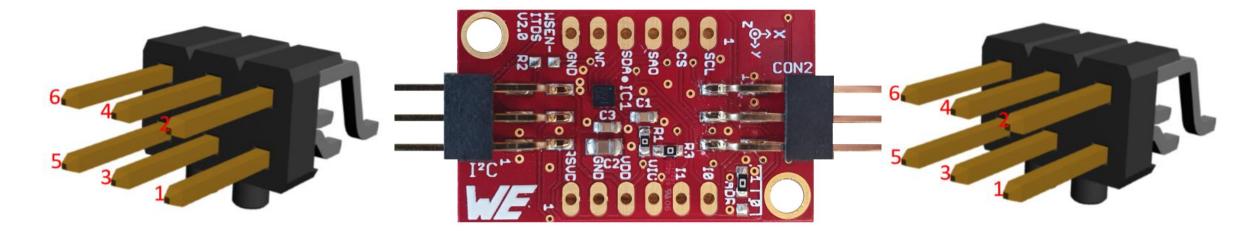


MEMS based capacitive sensing principle Integrated Temperature Sensor I<sup>2</sup>C and SPI digital interface

https://www.we-online.com/catalog/en/WSEN-EVAL\_ITDS

- ✓ 2 x 2 x 0.7mm
- ✓ 1.7v to 3.6v
- ✓ -40 °C up to +85 °C
- ✓ 32 level FIFO buffer
- ✓ 100nA sleep current
- ✓ 16µA to 155µA operating current
- ✓ ODR up to 1600, 400Hz
- ✓ Full scale ±2 g, ±4 g, ±8 g, ±16 g
- ✓ Max acceleration = 3000 g
- ✓ Drift with Temperature =  $\pm 2 \text{ mg/}^{\circ}\text{C}$
- ✓ Thermal accuracy =  $\pm 15$  °C
- ✓ Free fall offset =  $\pm 30$  mg
- ✓ Sensitivity / accuracy ±3 %
- ✓ Low Noise Density 90  $\mu$ g√Hz
- ✓ 2 x Interrupts = Free-fall, wake-up, tap, activity, motion and orientation detection

## ITDS – Accelerometer Eval board



Pin No	I <sup>2</sup> C Pins (CON1)	
1	GND	
2	SCL	
3	SDA	
4	GND	
5	NC	
6	VDD	

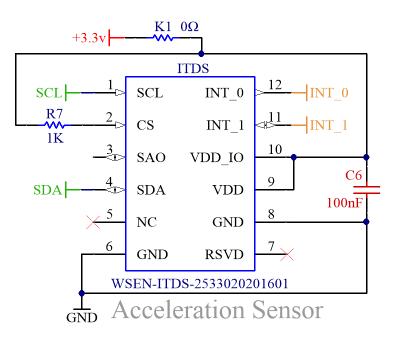
I2C Address = 0011 001b = 0x31

Pin No	SPI Pins (CON2)	
1	GND	
2	SCL	
3	SDA (MOSI)	
4	CS	
5	SAO (MISO)	
6	VDD	

SPI = remove R3 and ADR resistors

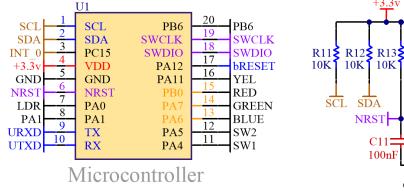


## ITDS – Accelerometer to MCU Interface



SAO pin is for I2C address selection or SPI SDO

Interrupts and external pull-up resistors are optional, depends on the MCU type.



+<u>3.3</u>v

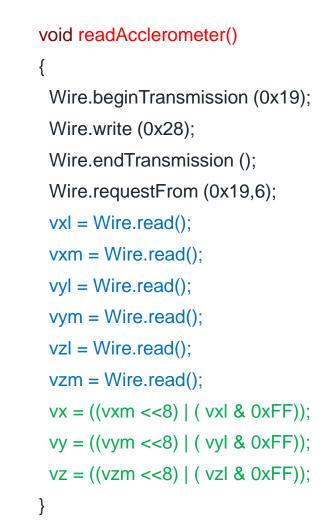
C11

100nF

GND

C10

100nF

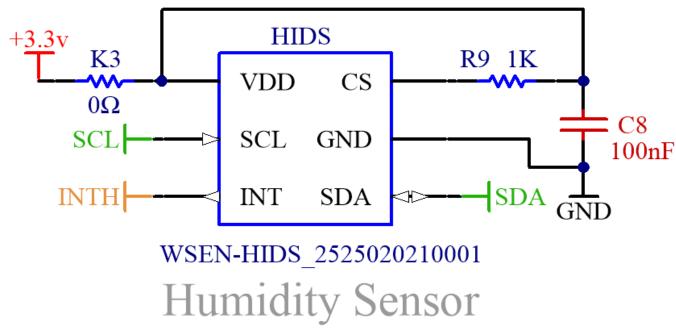


# **HUMIDITY SENSOR**



https://www.we-online.com/catalog/en/WSEN-HIDS

## HIDS – Schematic and PCB Guidelines:



- ✓ MEMS based capacitive sensing principle
- ✓ Relative humidity range 0% to 100%
- $\checkmark\,$  Calibrated 16 bit humidity and temperature output
- F ✓ I<sup>2</sup>C and SPI communication
  - ✓ Output data rate up to 12.5 Hz
  - ✓ Operating temperature range: -40 °C to 120 °C

# ABSOLUTE PRESSURE SENSOR



https://www.we-online.com/catalog/en/WSEN-PADS

## **Pressure basics**

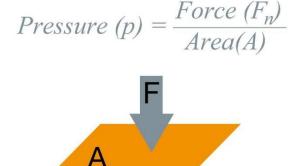
## 1 Newton force applied on an area of 1 meter<sup>2</sup> exerts Pressure of 1 Pascal (N/m<sup>2</sup>) = 0.01 mbar

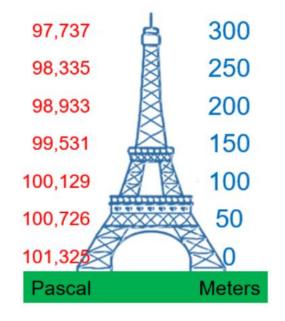
Vacuum = 0 bar Atmosphere = 996mbar ~ 1bar

0.01 mbar = 1 pa 1mbar = 100 pa 1 bar = 100,000pa = 100 kpa

### Pressure Sensor can be...

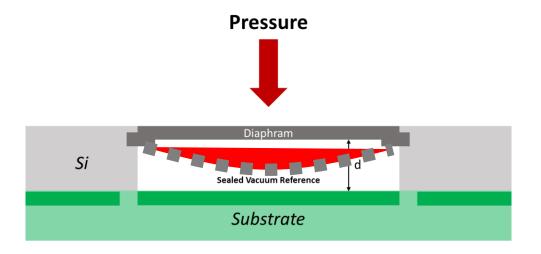
- o Optical
- o Piezo electric
- o Piezo resistive
- Magnetic
- o Membrane
- Capacitive
- MEMS based





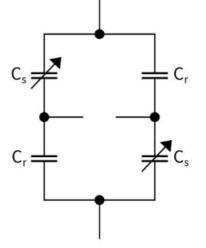


## <u>Capacitive MEMS – Pressure sensor</u>



$$\mathbf{C} = \varepsilon_0 \varepsilon_r \frac{A}{d}$$

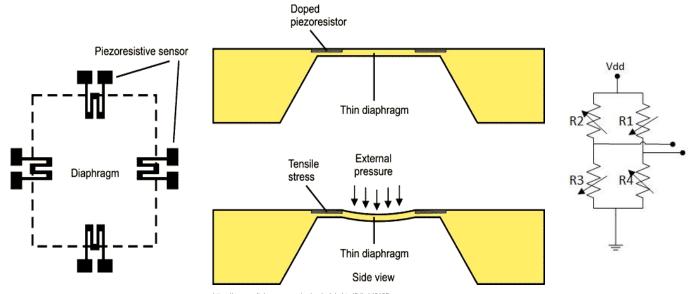
## Wheatstone Bridge Configuration:



- ✓ Less thermal drift
- ✓ Tolerant to short-term over pressure
- Ø Non-linear o/p
- Ø Low SNR
- Ø Low dynamic range
- Ø Hard to manufacture



## <u>Piezo Resistive – Pressure sensor</u>

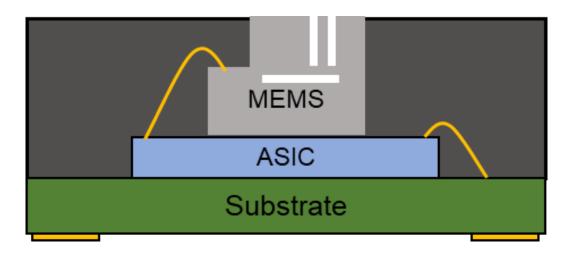


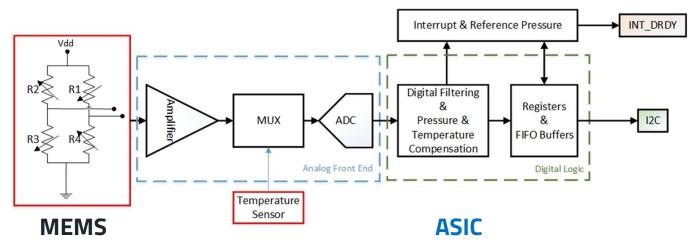
https://www.radiolocman.com/review/article.html?di=148185

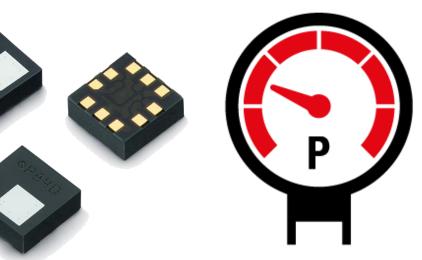
✓ Very linear result
 ✓ Easy to produce
 Ø Sensitive to temperature
 Ø Need frequent calibration



## PADS – MEMS Based Absolute Pressure Sensor







### PADS – MEMS

- Increased robustness
- Reduced contamination risk
- Best moisture and dust resistance
- o Multiple vent capillaries
- Factory calibrated at multiple temp.
- Calibration values stored locally



## PADS – Schematic and Firmware:

#### void readPADS(){ // STM32 IDE

/// https://www.we-online.de/catalog/en/WSEN-PADS //static const uint8\_t padsAddress = 0x5D <<1;</pre>

//static const uint8 t padsAddress = 0x5C <<1;</pre>

#### iBuf[0] = 0x28;

✓ FIFO buffer

✓ Built in thermometer

 $\checkmark$  ±1.5 °C temp accuracy

✓ Two I2C address choices

✓ 24 bit pressure reading

✓ Programmable interrupt

✓ 16 bit temperature reading

 $\checkmark$  ± 1 mbar absolute accuracy

✓ 4 to 12 µA operating current

✓ Low noise altitude detection 6-8 cm

uint8\_t ret = HAL\_I2C\_Master\_Transmit(&hi2c1, padsAddress, iBuf, 1, HAL\_MAX\_DELAY); if( ret != HAL\_OK){ beep; } // error beep, if sensor is removed.

### iBuf[0] = 0x28;

ret = HAL\_I2C\_Master\_Receive(&hi2c1, padsAddress, iBuf, 6, 50);

#### K2 0Ω +3.3vPADS 10 VDD IO VDD SCL SCL GND RSVD GND 100nF GN**SDA SDA** INT **INTP** SAO CS R8 1K WSEN-PADS-2511020213301

Abs. Pressure Sensor

#### uint8\_t p1, p2, p3; p1 = iBuf[1]; p2 = iBuf[2];✓ 26 to 126 kPa range p3 = iBuf[3];padsT1 = iBuf[3]; ✓ 900 nA sleep current padsT2 = iBuf[4];✓ 1.7 to 3.6v DC voltage padsTemp = (padsT1 + padsT2\*256)\*0.01;

#### uint32\_t int32, mb;

int32	= p3*65536 + p2*256 +	p1;
mb	= int32/4096;	<pre>// Hectopascle = mBar</pre>
mBarLsb	= 0x00FF & mb;	

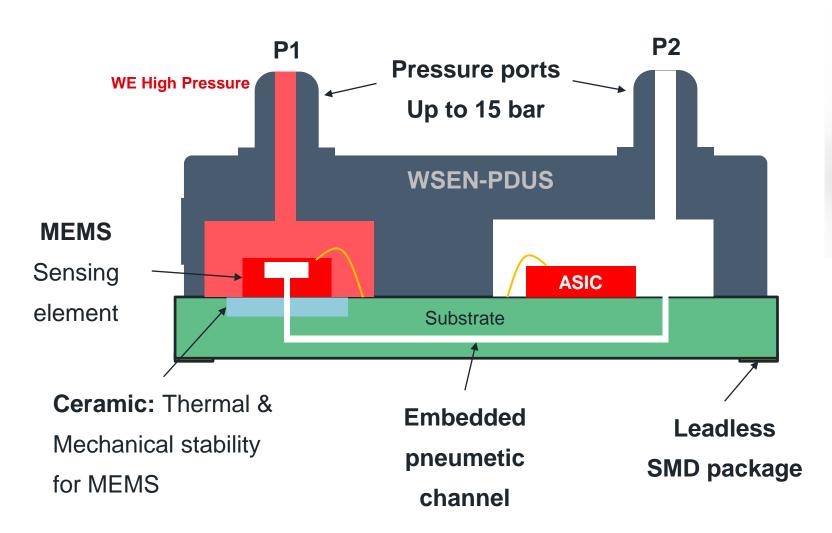
#### mBarMsb = mb >> 8;

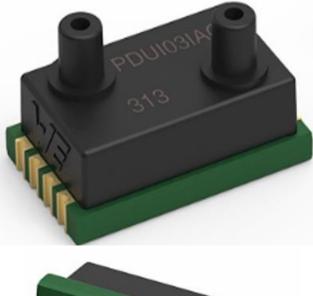
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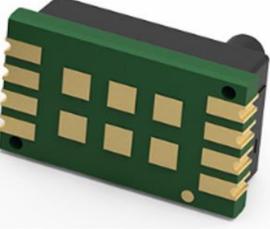
# DIFFERENTIAL PRESSURE SENSOR



## PDUS – MEMS based differential pressure sensor









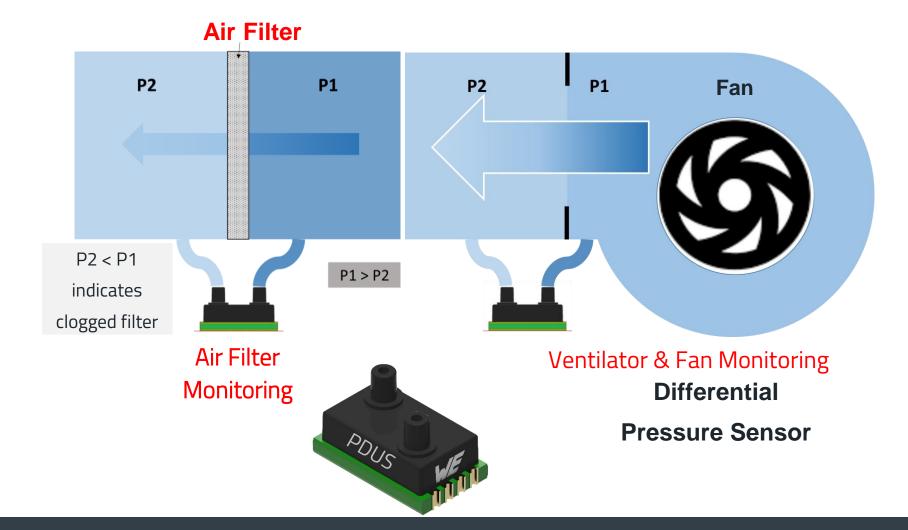
## PDUS – Differential pressure sensor eval board:



- ✓ 5v operations
- ✓ I2C and Analogue o/p
- ✓ High pressure up to 15 bar
- ✓ 15 bit data
- ✓ Individually calibrated
- ✓ 0 to 70°C compensated
- ✓ Supply (not a ratio metric o/p)
- ✓ 2mm Ø tube connections
- ✓ 4mm Ø adaptor nozzles
- ✓ Best mechanical stability
- ✓ Increased safety
- ✓ CAD files for customisation



## PDUS – Application, HVAC filter monitor



33



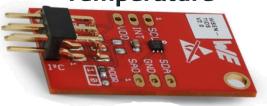
## **Sensor Experiment Tools:**

Free <u>samples</u> of actual sensors Free tech <u>support</u> FeatherWings + <u>Shield</u> Eval boards <u>GitHub</u> Libraries **Altium, Eagle, STP Libraries** *Code Examples PIC, ARM, Arduino, STM32 etc.* 

Humidity



## Temperature

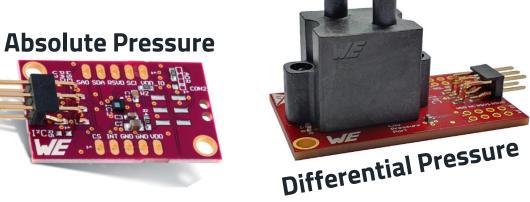




feathe

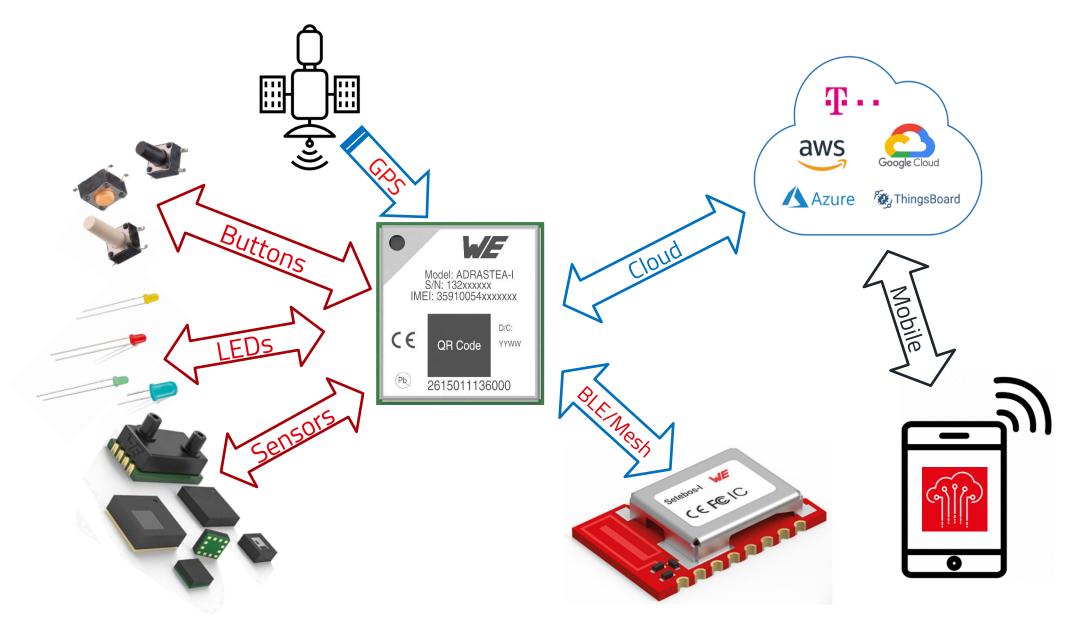
Acceleration

Sensor FeatherWing



Arduino Uno Sensor Shield





https://www.we-online.com/catalog/en/ADRASTEA-I





